

6.035

Unoptimized Code Generation

Orientation

- Source code
- Intermediate representation
- Unoptimized assembler
- Executable file
 - Data segments (initialized, zeroed, constant)
 - Code segments

Big Picture

- Starting point – Intermediate Representation
- Ending point – Generated Assembly Code
- Emphasis on UNOPTIMIZED
- Do simplest possible thing for now
- Will treat optimizations separately

Machines understand...

| LOCATION | DATA |
|----------|----------|
| 0046 | 8B45FC |
| 0049 | 4863F0 |
| 004c | 8B45FC |
| 004f | 4863D0 |
| 0052 | 8B45FC |
| 0055 | 4898 |
| 0057 | 8B048500 |
| | 000000 |
| 005e | 8B149500 |
| | 000000 |
| 0065 | 01C2 |
| 0067 | 8B45FC |
| 006a | 4898 |
| 006c | 89D7 |
| 006e | 033C8500 |
| | 000000 |
| 0075 | 8B45FC |
| 0078 | 4863C8 |
| 007b | 8B45F8 |
| 007e | 4898 |
| 0080 | 8B148500 |

Machines understand...

| LOCATION | DATA | ASSEMBLY INSTRUCTION |
|----------|--------------------|-----------------------|
| 0046 | 8B45FC | movl -4(%rbp), %eax |
| 0049 | 4863F0 | movslq %eax,%rsi |
| 004c | 8B45FC | movl -4(%rbp), %eax |
| 004f | 4863D0 | movslq %eax,%rdx |
| 0052 | 8B45FC | movl -4(%rbp), %eax |
| 0055 | 4898 | cltq |
| 0057 | 8B048500 000000 | movl B(,%rax,4), %eax |
| 005e | 8B149500 000000 | movl A(,%rdx,4), %edx |
| 0065 | 01C2 | addl %eax, %edx |
| 0067 | 8B45FC | movl -4(%rbp), %eax |
| 006a | 4898 | cltq |
| 006c | 89D7 | movl %edx, %edi |
| 006e | 033C8500 000000 | addl C(,%rax,4), %edi |
| 0075 | 8B45FC | movl -4(%rbp), %eax |
| 0078 | 4863C8 | movslq %eax,%rcx |
| 007b | 8B45F8 | movl -8(%rbp), %eax |
| 007e | 4898 | cltq |
| 0080 | 8B148500 | movl B(,%rax,4), %edx |

Assembly language

- Advantages
 - Simplifies code generation due to use of symbolic instructions and symbolic names
 - Logical abstraction layer
 - Many different architectures implement same ISA
- Disadvantages
 - Additional process of assembling and linking
 - Assembler adds overhead

Assembly language

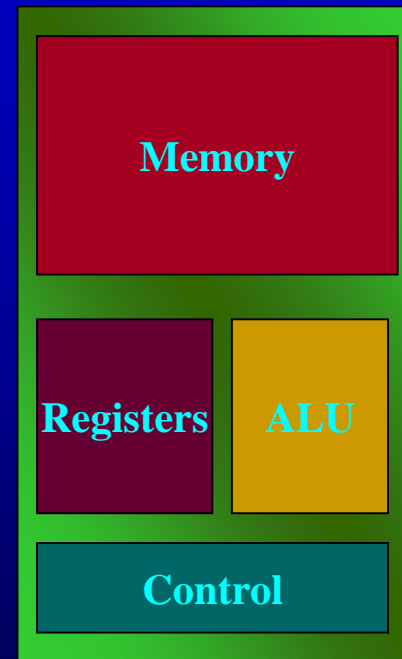
- Relocatable machine language (object modules)
 - all locations(addresses) represented by symbols
 - Mapped to memory addresses at link and load time
 - Flexibility of separate compilation
- Absolute machine language
 - addresses are hard-coded
 - simple and straightforward implementation
 - inflexible -- hard to reload generated code
 - Used in interrupt handlers and device drivers

Concept of An Object File

- The object file has:
 - Multiple Segments
 - Symbol Information
 - Relocation Information
- Segments
 - Global Offset Table
 - Procedure Linkage Table
 - Text (code)
 - Data
 - Read Only Data
- To run program, OS reads object file, builds executable process in memory, runs process
- We will use assembler to generate object files

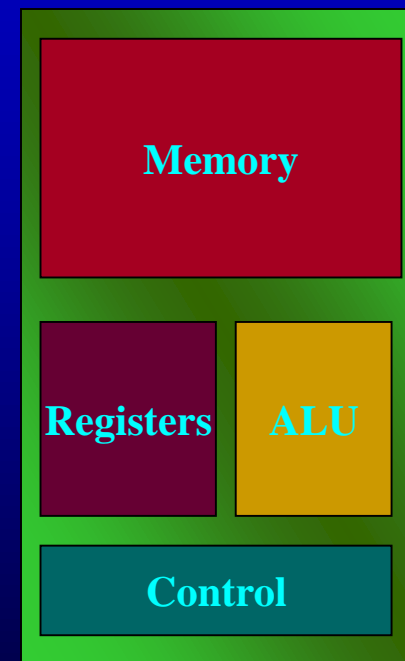
Overview of a modern ISA

- Memory
- Registers
- ALU
- Control

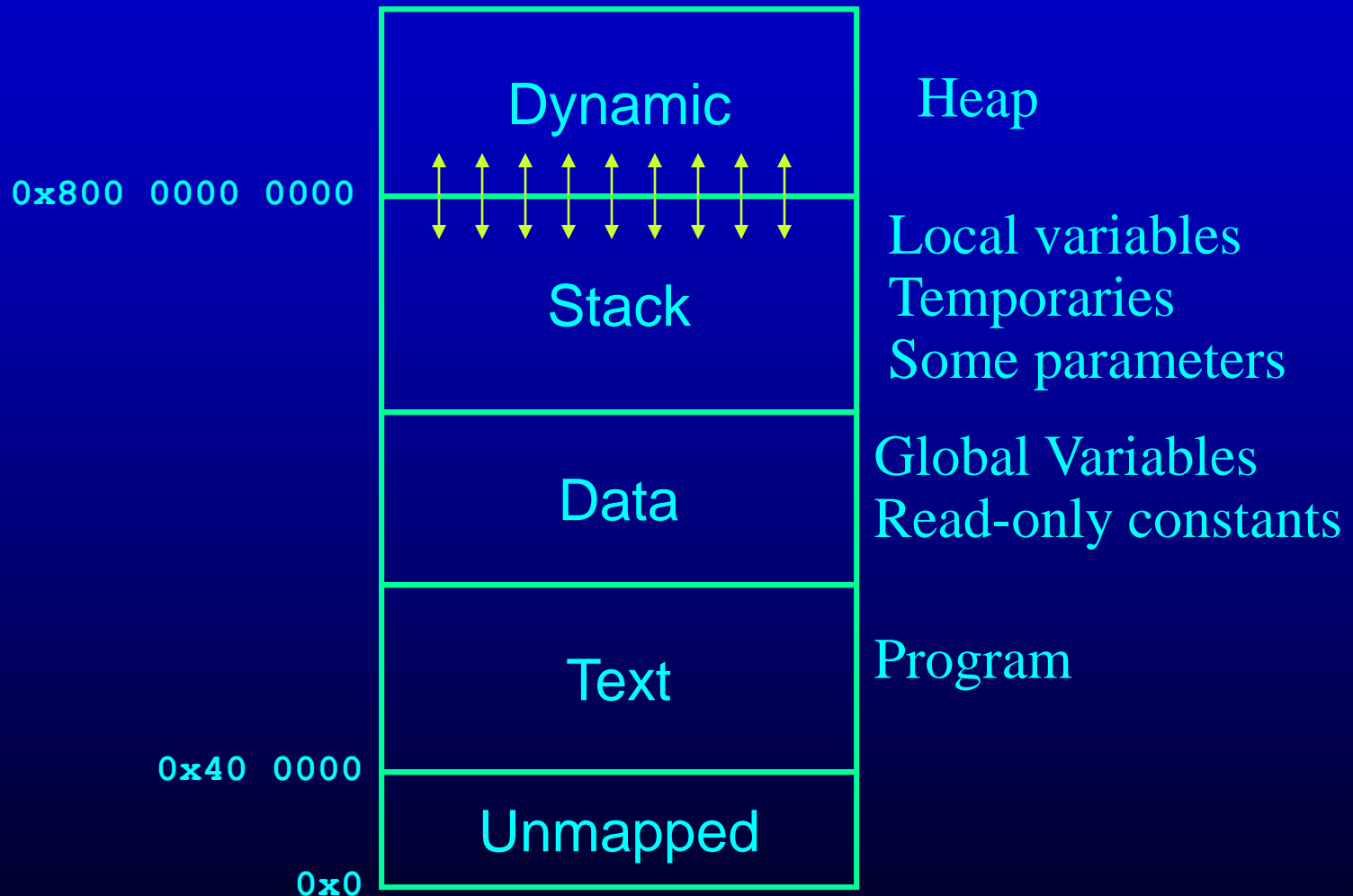


From IR to Assembly

- Data Placement and Layout
 - Global variables
 - Constants (strings, numbers)
 - Object fields
 - Parameters, local variables
 - Temporaries
- Code
 - Read and write data
 - Compute
 - Flow of control



Typical Memory Layout



Generated Assembler

```
int a[10];  
int count;
```

```
.bss  
.global_count:  
    .zero 8  
.global_a:  
    .zero 80
```

Example (Illustrative, Not Definitive)

```
int PlusOne(int p) {  
    int t;  
    t = 1;  
    return p+t;  
}
```

```
.method_PlusOne:  
    PUSH_ALL_REGS  
    subq $48, %rsp  
    movq 128(%rsp), %rax  
    movq %rax, 40(%rsp)  
.node_41:  
    movq 40(%rsp), %rax  
    movq %rax, 32(%rsp)  
    movq $0, 24(%rsp)  
    movq $1, 24(%rsp)  
    movq 32(%rsp), %rax  
    movq %rax, 16(%rsp)  
    movq 24(%rsp), %rax  
    movq %rax, 8(%rsp)  
    movq 16(%rsp), %rax  
    addq 8(%rsp), %rax  
    movq %rax, (%rsp)  
    movq (%rsp), %rax  
    movq %rax, 160(%rsp)  
    addq $48, %rsp  
    POP_ALL_REGS  
    ret
```

```
int increment() {  
    count = count + 1;  
    return count;  
}
```

```
.method_increment:  
    PUSH_ALL_REGS  
    subq $24, %rsp  
.node_61:  
    movq .global_count, %rax  
    movq %rax, 16(%rsp)  
    movq 16(%rsp), %rax  
    addq $1, %rax  
    movq %rax, 8(%rsp)  
    movq 8(%rsp), %rax  
    movq %rax, .global_count  
    movq .global_count, %rax  
    movq %rax, (%rsp)  
    movq (%rsp), %rax  
    movq %rax, 136(%rsp)  
    addq $24, %rsp  
    POP_ALL_REGS  
    ret
```

```
int sign(int p) {
    if (p < 0) {
        return -1;
    } else {
        if (p > 0) {
            return 1;
        } else {
            return 0;
        }
    }
}
```

```
.method_sign:
    PUSH_ALL_REGS
    subq $48, %rsp
    movq 128(%rsp), %rax
    movq %rax, 40(%rsp)
.node_110:
    movq 40(%rsp), %rax
    movq %rax, 32(%rsp)
    movq 32(%rsp), %rax
    movq %rax, 24(%rsp)
    cmpq $0, 24(%rsp)
    movq $0, %rax
    setl %al
    movq %rax, 16(%rsp)
    cmpq $0, 24(%rsp)
    jl .node_111
    jmp .node_112
.node_112:
    movq 32(%rsp), %rax
    movq %rax, 8(%rsp)
    cmpq $0, 8(%rsp)
    movq $0, %rax
    setg %al
    movq %rax, (%rsp)
    movq $0, %rax
    cmpq 8(%rsp), %rax
    jl .node_113
    jmp .node_114
```

```
int sign(int p) {  
    if (p < 0) {  
        return -1;  
    } else {  
        if (p > 0) {  
            return 1;  
        } else {  
            return 0;  
        }  
    }  
}
```

```
.node_114:  
    movq $0, 160(%rsp)  
    addq $48, %rsp  
    POP_ALL_REGS  
    ret  
.node_113:  
    movq $1, 160(%rsp)  
    addq $48, %rsp  
    POP_ALL_REGS  
    ret  
.node_111:  
    movq $-1, 160(%rsp)  
    addq $48, %rsp  
    POP_ALL_REGS  
    ret
```


Exploring Assembly Patterns

```
struct { int x, y; double z; } b;
```

```
int g;
```

```
int a[10];
```

```
char *s = "Test String";
```

```
int f(int p) {
```

```
    int i;
```

```
    int s;
```

```
    s = 0.0;
```

```
    for (i = 0; i < 10; i++) {
```

```
        s = s + a[i];
```

```
    }
```

```
    return s;
```

```
}
```

- gcc -g -S t.c
- vi t.s

Global Variables

C

```
struct { int x, y; double z; } b;
```

```
int g;
```

```
int a[10];
```

Assembler directives (reserve space in data segment)

```
.comm _a,40,4      ## @a
```

```
.comm _b,16,3     ## @b
```

```
.comm _g,4,2      ## @g
```

Name **Size** **Alignment**

Addresses

Reserve Memory

```
.comm _a,40,4      ## @a  
.comm _b,16,3     ## @b  
.comm _g,4,2      ## @g
```

Define 3 constants

_a – address of a in data segment
_b – address of b in data segment
_g – address of g in data segment

Struct and Array Layout

- `struct { int x, y; double z; } b;`
 - Bytes 0-1: x
 - Bytes 2-3: y
 - Bytes 4-7: z
- `int a[10]`
 - Bytes 0-1: a[0]
 - Bytes 2-3: a[1]
 - ...
 - Bytes 18-19: a[9]

Dynamic Memory Allocation

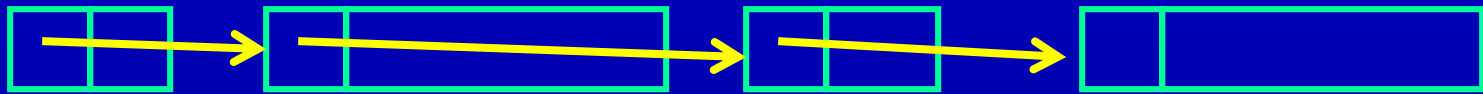
```
typedef struct { int x, y; } PointStruct, *Point;  
Point p = malloc(sizeof(PointStruct));
```

What does allocator do?

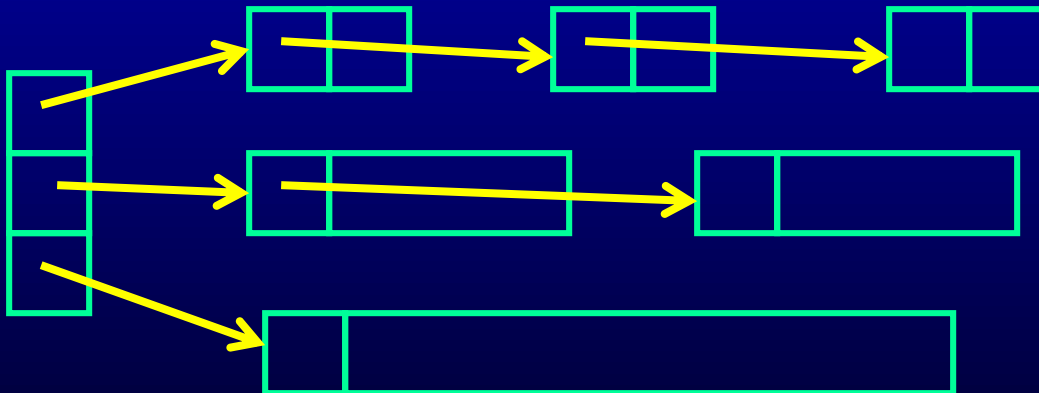
- returns next free big enough data block in heap
- appropriately adjusts heap data structures

Some Heap Data Structures

- Free List (arrows are addresses)



- Powers of Two Lists

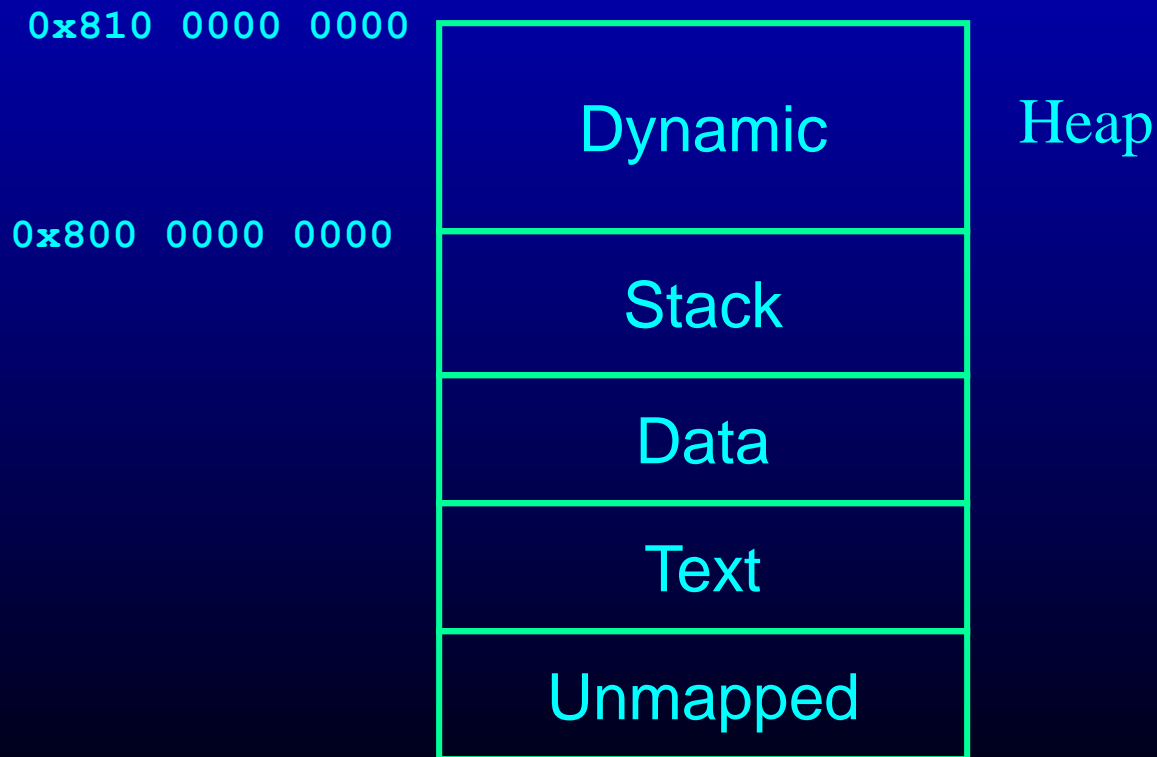


Getting More Heap Memory

Scenario: Current heap goes from `0x800 0000 000`- `0x810 0000 000`

Need to allocate large block of memory

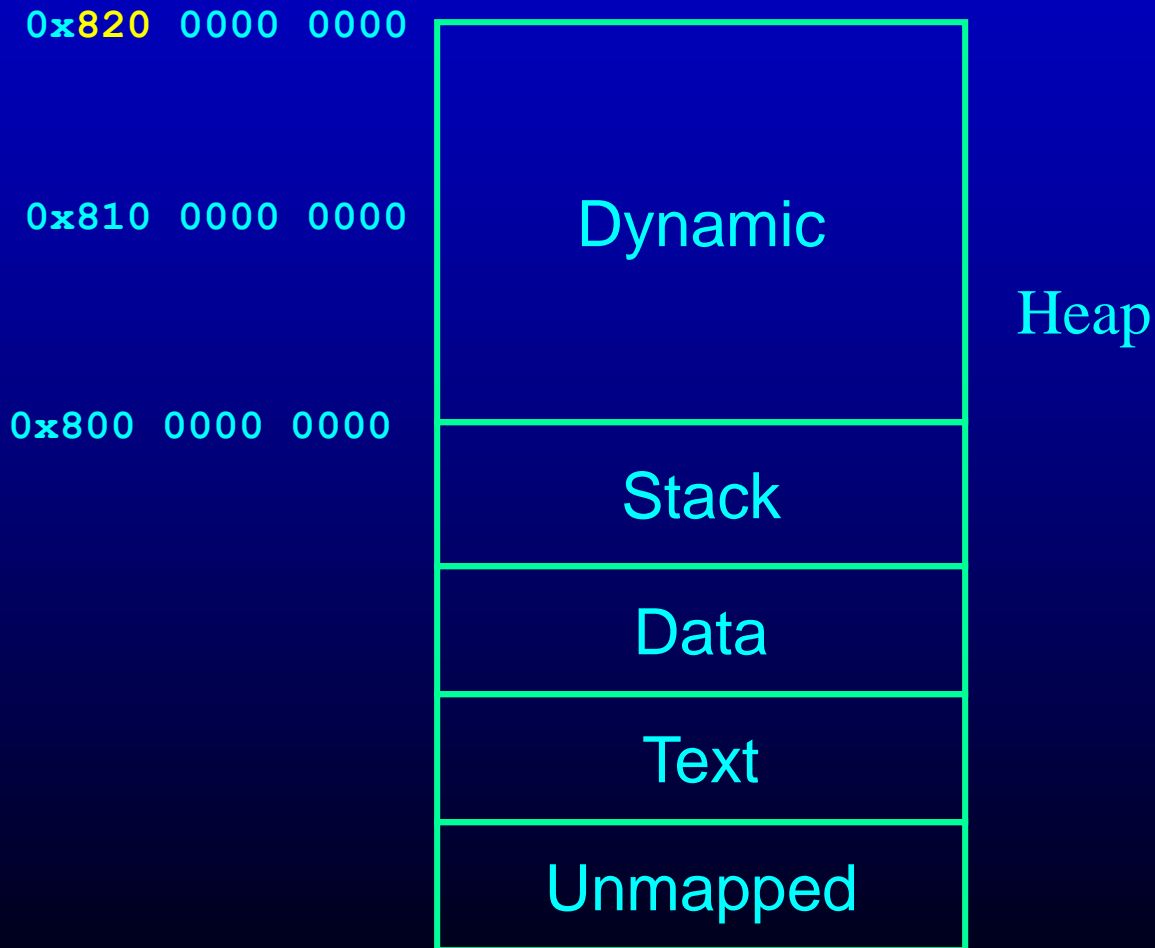
No block that large available



Getting More Heap Memory

Solution: Talk to OS, increase size of heap (sbrk)

Allocate block in new heap



The Stack

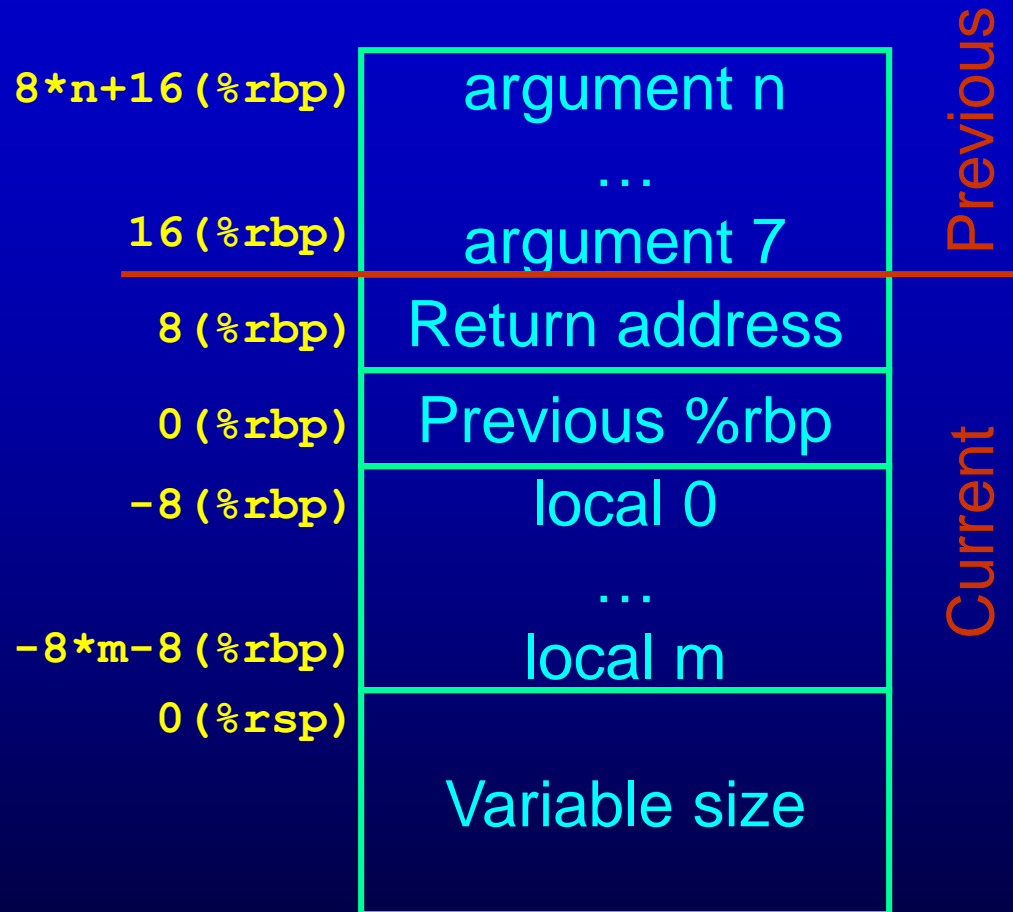
- Arguments 0 to 6 are in:
 - %rdi, %rsi, %rdx,
 - %rcx, %r8 and %r9

%rbp

- marks the beginning of the current frame

%rsp

- marks the end

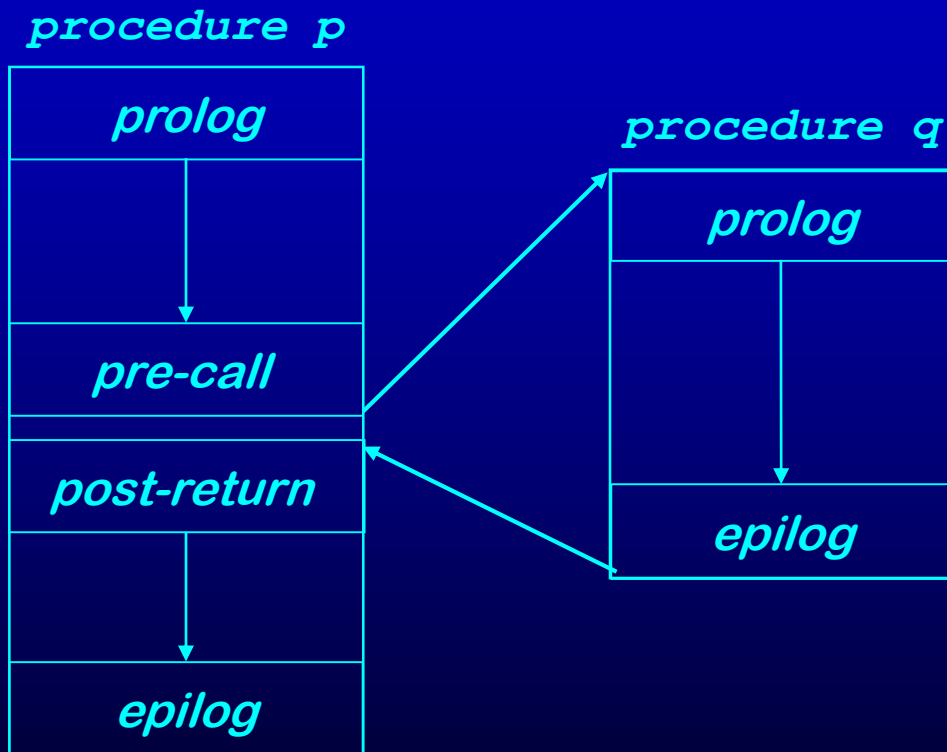


Question:

- Why use a stack? Why not use the heap or pre-allocated in the data segment?

Procedure Linkages

Standard procedure linkage



Pre-call:

- Save caller-saved registers
- Push arguments

Prolog:

- Push old frame pointer
- Save callee-saved registers
- Make room for temporaries

Epilog:

- Restore callee-saved
- Pop old frame pointer
- Store return value

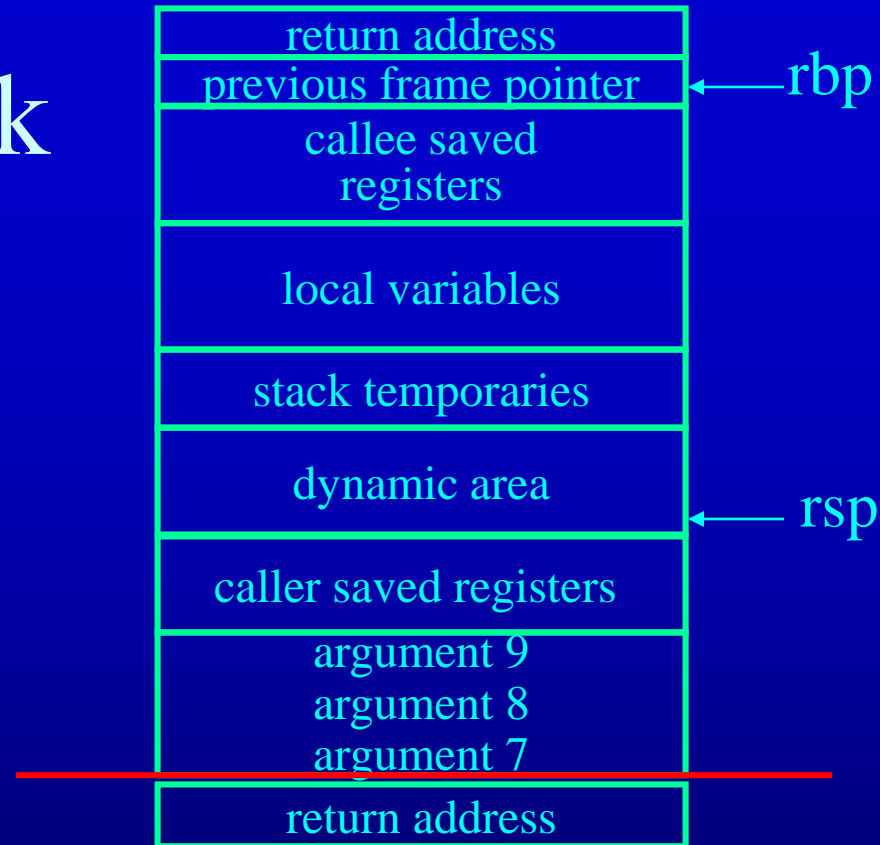
Post-return:

- Restore caller-saved
- Pop arguments

Stack

- Calling: Caller
 - Assume %rcx is live and is caller save
 - Call foo(A, B, C, D, E, F, G, H, I)
 - A to I are at -8(%rbp) to -72(%rbp)

```
push    %rcx
push    -72(%rbp)
push    -64(%rbp)
push    -56(%rbp)
mov     -48(%rbp), %r9
mov     -40(%rbp), %r8
mov     -32(%rbp), %rcx
mov     -24(%rbp), %rdx
mov     -16(%rbp), %rsi
mov     -8(%rbp), %rdi
call   foo
```

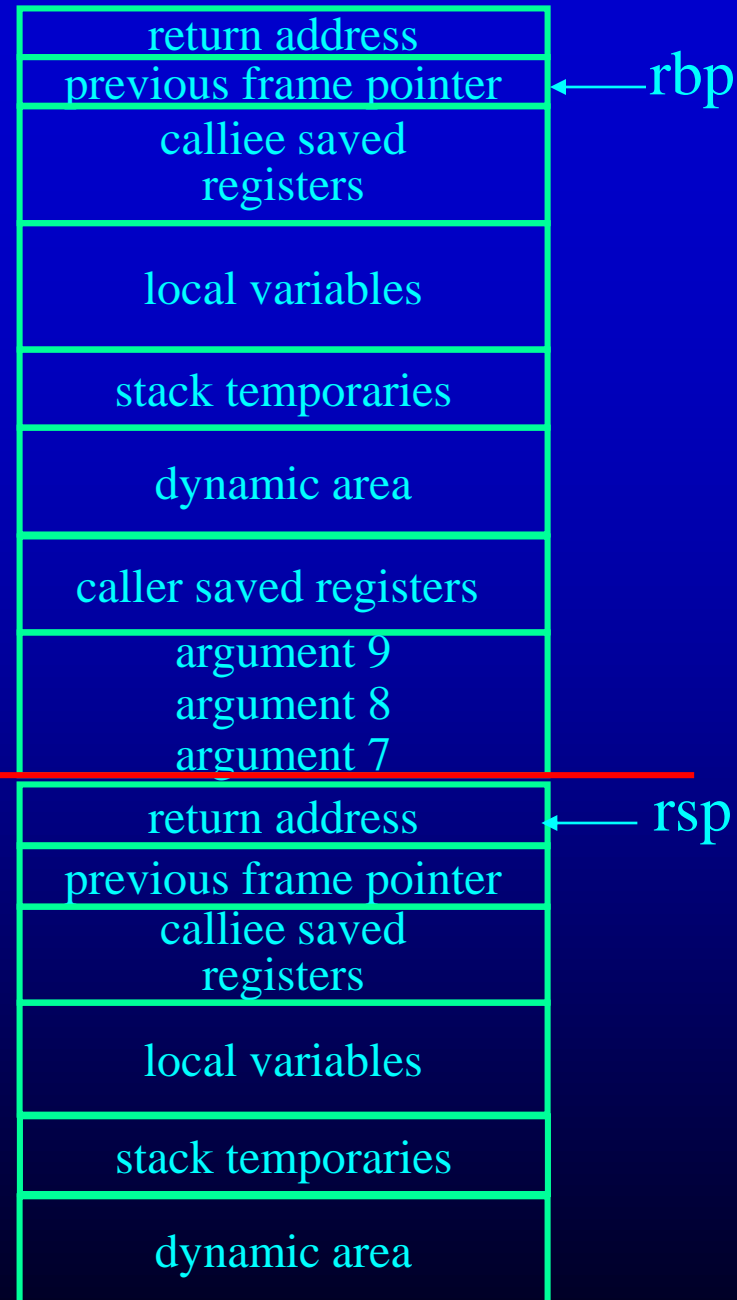


Stack

- Calling: Callee
 - Assume %rbx is used in the function and is callee save
 - Assume 40 bytes are required for locals

foo:

```
push    %rbp
mov     %rsp, %rbp
enter  $48, $0
sub     $48, %rsp
mov     %rbx, -8(%rbp)
```



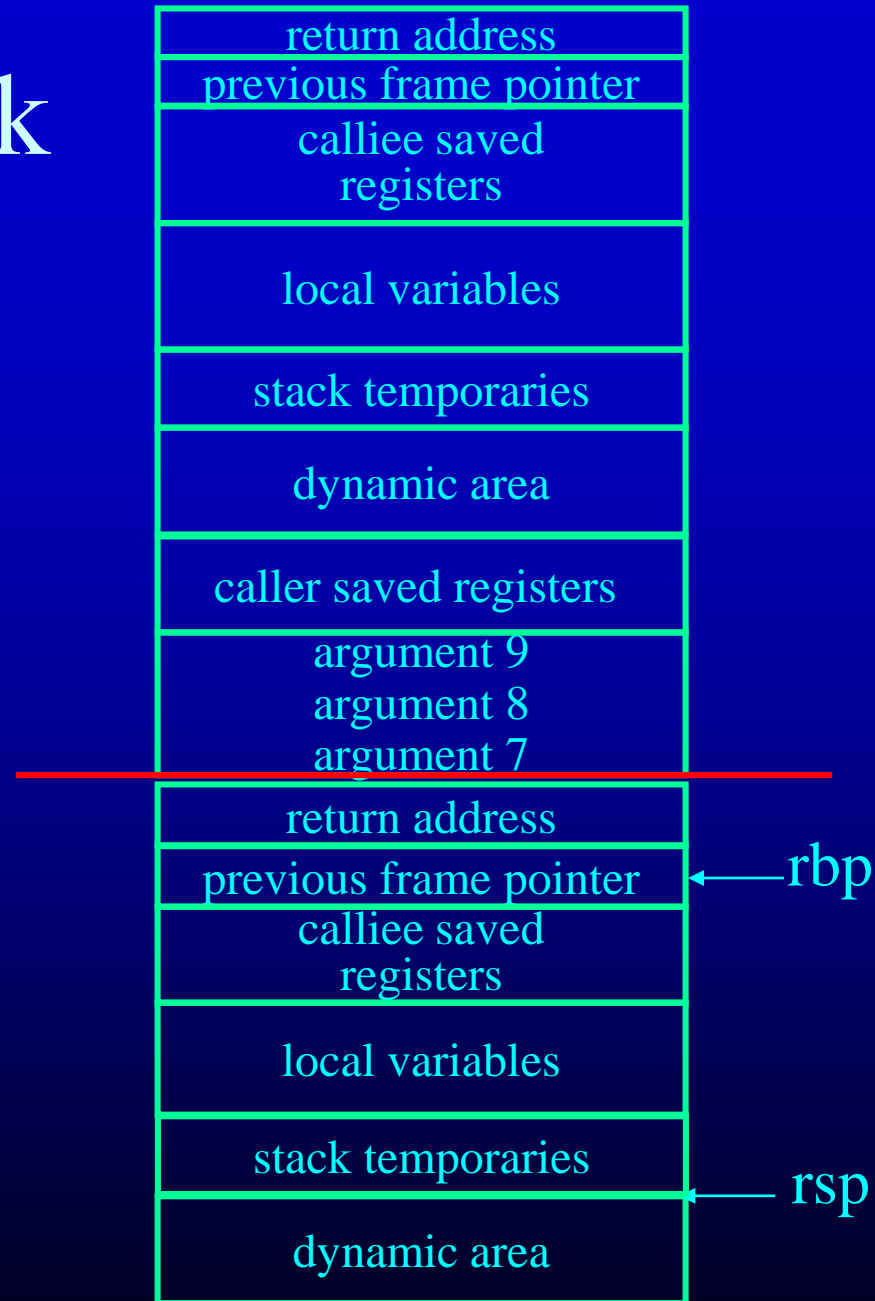
Stack

- Arguments
- Call foo(A, B, C, D, E, F, G, H, I)
 - Passed in by pushing before the call

```
push    -72(%rbp)
push    -64(%rbp)
push    -56(%rbp)
mov     -48(%rbp), %r9
mov     -40(%rbp), %r8
mov     -32(%rbp), %rcx
mov     -24(%rbp), %rdx
mov     -16(%rbp), %rsi
mov     -8(%rbp), %rdi
call   foo
```

- Access A to F via registers
 - or put them in local memory
- Access rest using 16+xx(%rbp)

```
mov     16(%rbp), %rax
mov     24(%rbp), %r10
```



Stack

- Locals and Temporaries

- Calculate the size and allocate space on the stack

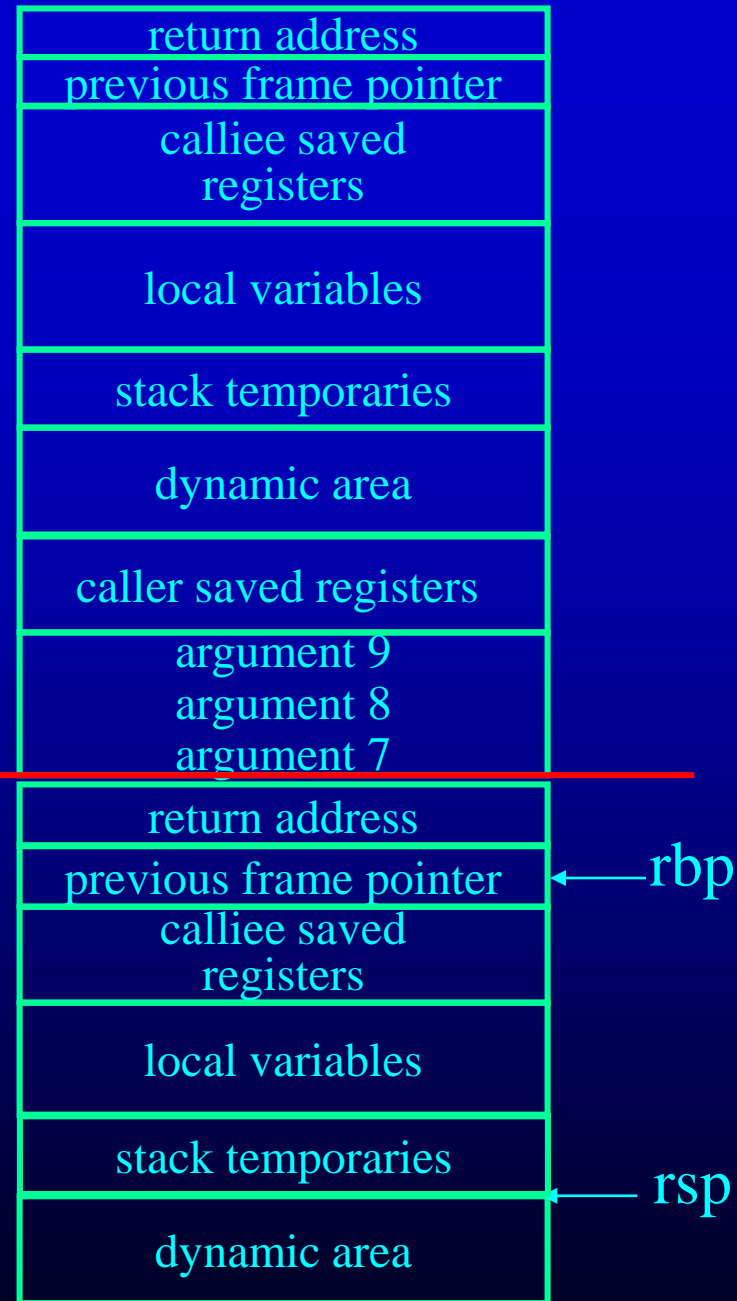
```
sub    $48, %rsp
```

```
or    enter    $48, 0
```

- Access using `-8-xx(%rbp)`

```
mov    -28(%rbp), %r10
```

```
mov    %r11, -20(%rbp)
```

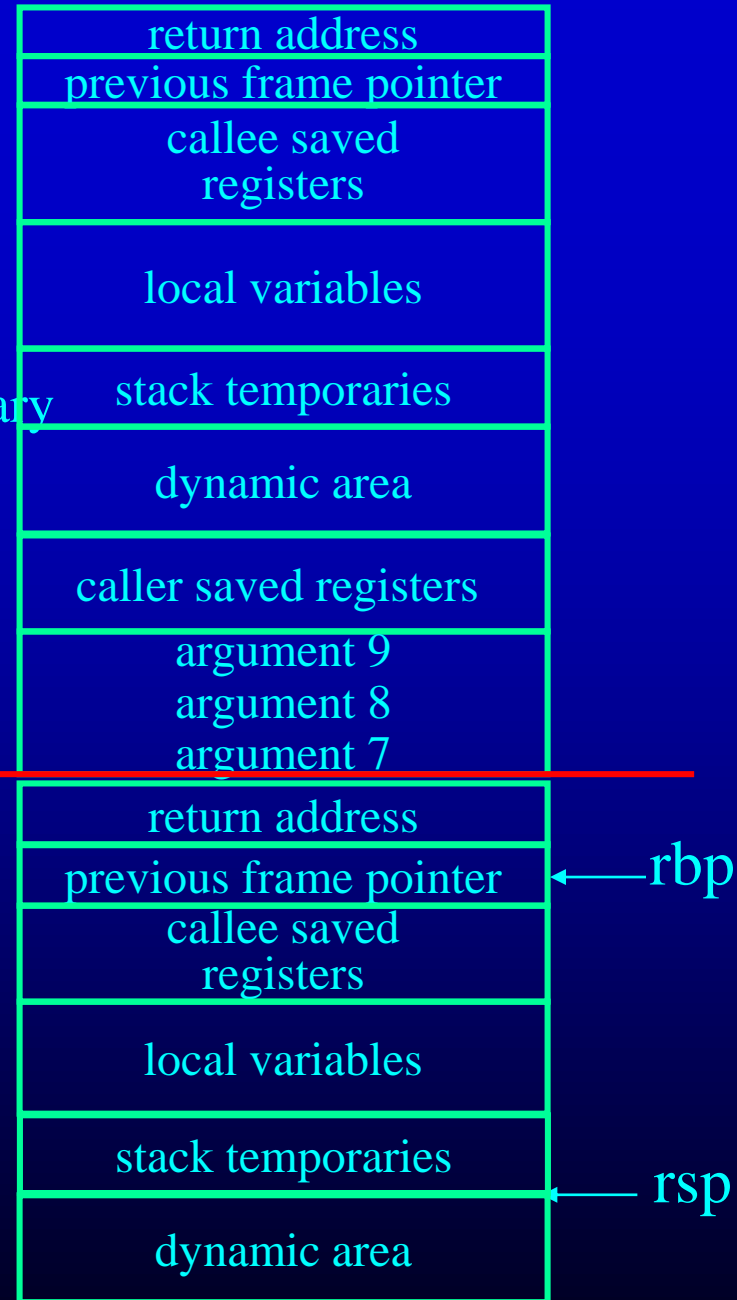


Stack

- Returning Callee

- Assume the return value is the first temporary
- Restore the caller saved register
- Put the return value in %rax
- Tear-down the call stack

```
mov    -8(%rbp), %rbx
mov    -16(%rbp), %rax
mov    leave    %rbp, %rsp
pop    %rbp
ret
```



Stack

- Returning Caller
- Assume the return value goes to the first temporary
 - Restore the stack to reclaim the argument space
 - Restore the caller save registers
 - Save the return value



```
call    foo
add     $24, %rsp
pop     %rcx
mov     %rax, 8(%rbp)
...
```

Question:

- Do you need the \$rbp?
- What are the advantages and disadvantages of having \$rbp?

So far we covered..

CODE

Procedures

Control Flow

Statements

Data Access

DATA

Global Static Variables

Global Dynamic Data

Local Variables

Temporaries

Parameter Passing

Read-only Data

Outline

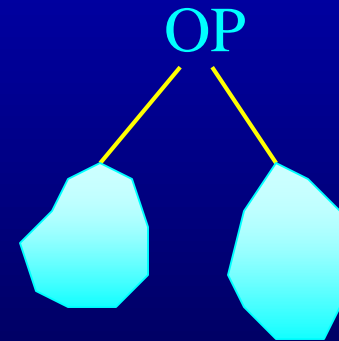
- Generation of expressions and statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

Expressions

- Expressions are represented as trees
 - Expression may produce a value
 - Or, it may set the condition codes (boolean exprs)
- How do you map expression trees to the machines?
 - How to arrange the evaluation order?
 - Where to keep the intermediate values?
- Two approaches
 - Stack Model
 - Flat List Model

Evaluating expression trees

- Stack model
 - Eval left-sub-tree
Put the results on the stack
 - Eval right-sub-tree
Put the results on the stack
 - Get top two values from the stack
perform the operation OP
put the results on the stack
- Very inefficient!



Evaluating expression trees

- Flat List Model
 - The idea is to linearize the expression tree
 - Left to Right Depth-First Traversal of the expression tree
 - Allocate temporaries for intermediates (all the nodes of the tree)
 - New temporary for each intermediate
 - All the temporaries on the stack (for now)
 - Each expression is a single 3-addr op
 - $x = y \text{ op } z$
 - Code generation for the 3-addr expression
 - Load y into register %r10
 - Load z into register %r11
 - Perform `op %r10, %r11`
 - Store %r11 to x

Issues in Lowering Expressions

- Map intermediates to registers?
 - registers are limited
 - when the tree is large, registers may be insufficient \Rightarrow allocate space in the stack
- No machine instruction is available
 - May need to expand the intermediate operation into multiple machine ops.
- Very inefficient
 - too many copies
 - don't worry, we'll take care of them in the optimization passes
 - keep the code generator very simple

What about statements?

- Assignment statements are simple
 - Generate code for RHS expression
 - Store the resulting value to the LHS address
- But what about conditionals and loops?

Outline

- Generation of statements
- Generation of control flow
- Guidelines in writing a code generator

Two Techniques

- Template Matching
- Short-circuit Conditionals
- Both are based on structural induction
 - Generate a representation for the sub-parts
 - Combine them into a representation for the whole

Template for conditionals

```
if (test)
    true_body
else
    false_body
```

```
        <do the test>
        joper lab_true
        <false_body>
        jmp    lab_end
lab_true:
        <true_body>
lab_end:
```

Example Program

```
if (ax > bx)
    dx = ax - bx;
else
    dx = bx - ax;
```

<do test>

joper .L0

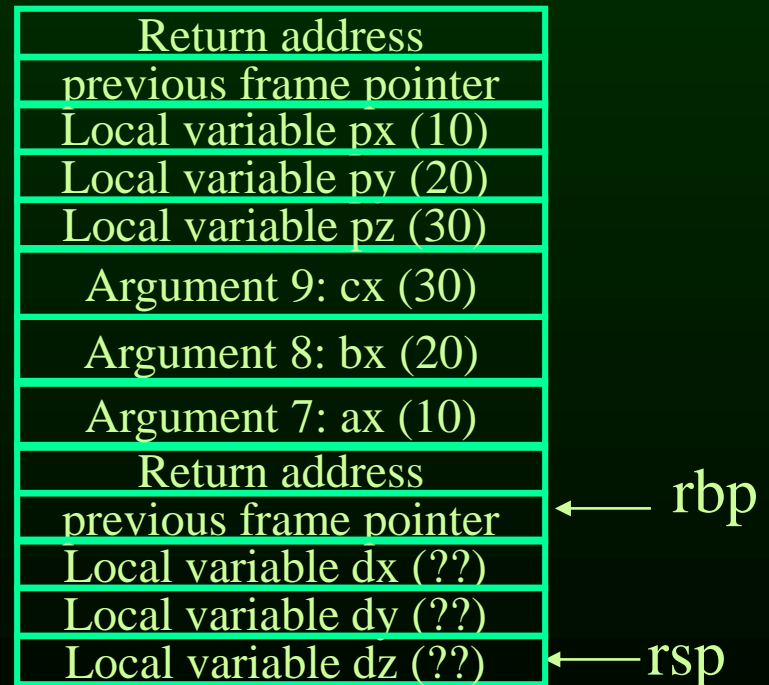
<FALSE BODY>

jmp .L1

.L0:

<TRUE BODY>

.L1:



Example Program

```
if (ax > bx)
    dx = ax - bx;
else
    dx = bx - ax;
```

```
movq    16(%rbp), %r10
movq    24(%rbp), %r11
cmpq    %r10, %r11
jg      .L0
```

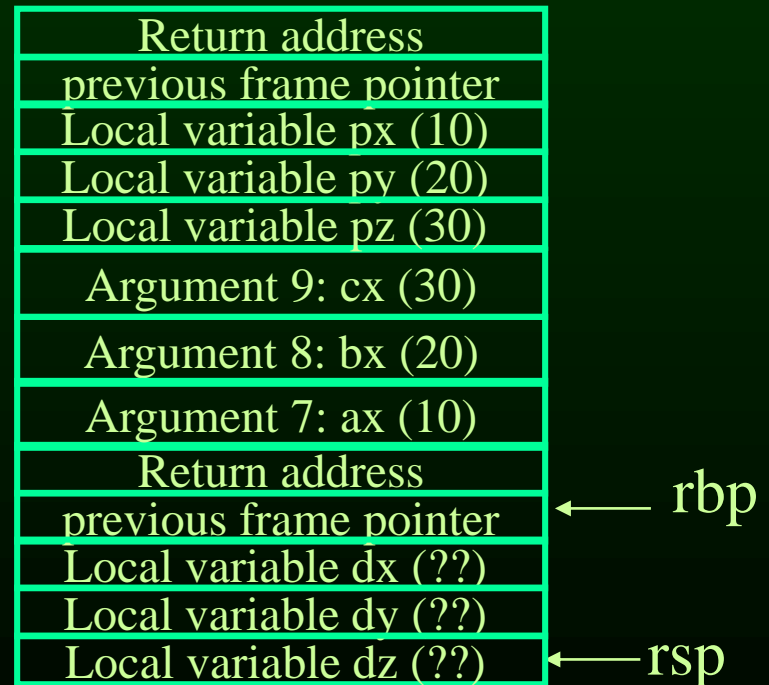
<FALSE BODY>

```
jmp     .L1
```

.L0:

<TRUE BODY>

.L1:



Example Program

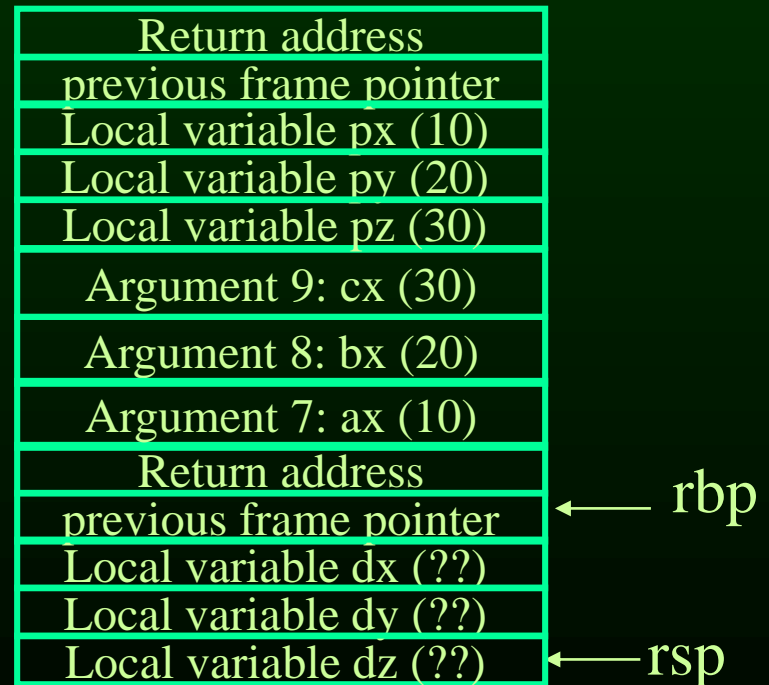
```
if (ax > bx)
    dx = ax - bx;
else
    dx = bx - ax;
```

```
movq    16(%rbp), %r10
movq    24(%rbp), %r11
cmpq    %r10, %r11
jg      .L0
movq    24(%rbp), %r10
movq    16(%rbp), %r11
subq    %r10, %r11
movq    %r11, -8(%rbp)
jmp     .L1
```

.L0:

<TRUE BODY>

.L1:



Example Program

```
if (ax > bx)
    dx = ax - bx;
else
    dx = bx - ax;
```

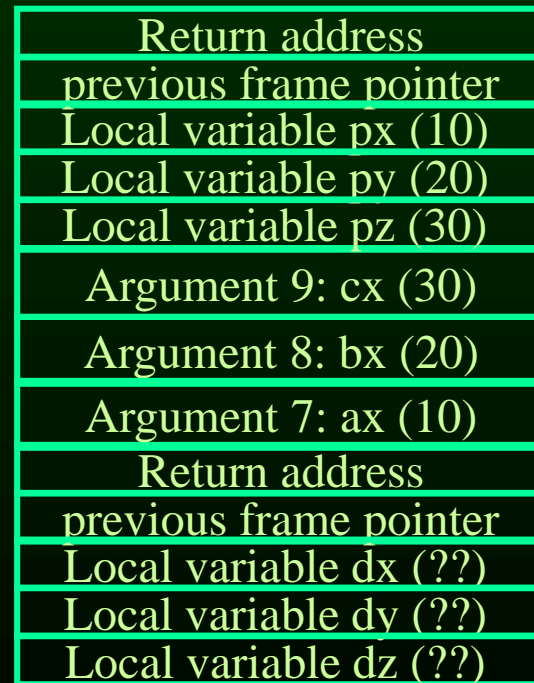
```
movq    16(%rbp), %r10
movq    24(%rbp), %r11
cmpq    %r10, %r11
jg      .L0
```

```
movq    24(%rbp), %r10
movq    16(%rbp), %r11
subq    %r10, %r11
movq    %r11, -8(%rbp)
jmp     .L1
```

.L0:

```
movq    16(%rbp), %r10
movq    24(%rbp), %r11
subq    %r10, %r11
movq    %r11, -8(%rbp)
```

.L1:



← rbp

← rsp

Template for while loops

```
while (test)  
    body
```

Template for while loops

```
while (test)
    body
lab_cont:
    <do the test>
    joper lab_body
    jmp    lab_end
lab_body:
    <body>
    jmp    lab_cont
lab_end:
```

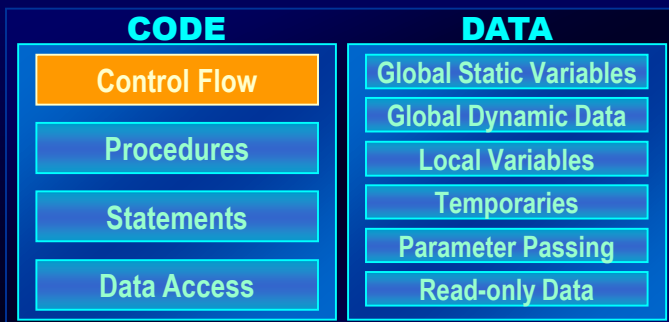
Template for while loops

```
while (test)
    body
```

```
lab_cont:
    <do the test>
    joper lab_body
    jmp    lab_end
lab_body:
    <body>
    jmp    lab_cont
lab_end:
```

- An optimized template

```
lab_cont:
    <do the test>
    joper lab_end
    <body>
    jmp    lab_cont
lab_end:
```



Question:

- What is the template for?

`do`

`body`

`while (test)`

Question:

- What is the template for?

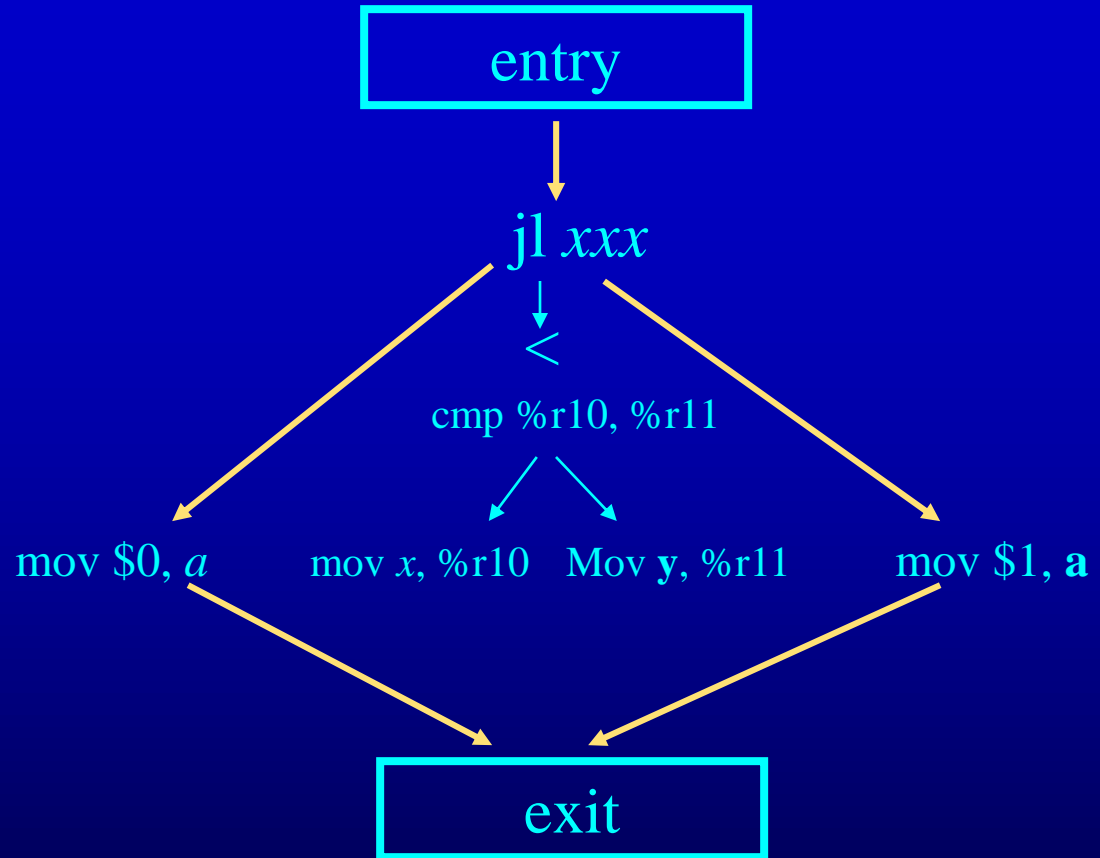
```
do
  body
while (test)
```

```
lab_begin:
    <body>
    <do test>
    joper lab_begin
```

Control Flow Graph (CFG)

- Starting point: high level intermediate format, symbol tables
- Target: CFG
 - CFG Nodes are Instruction Nodes
 - CFG Edges Represent Flow of Control
 - Forks At Conditional Jump Instructions
 - Merges When Flow of Control Can Reach A Point Multiple Ways
 - Entry and Exit Nodes

```
if (x < y) {  
    a = 0;  
} else {  
    a = 1;  
}
```



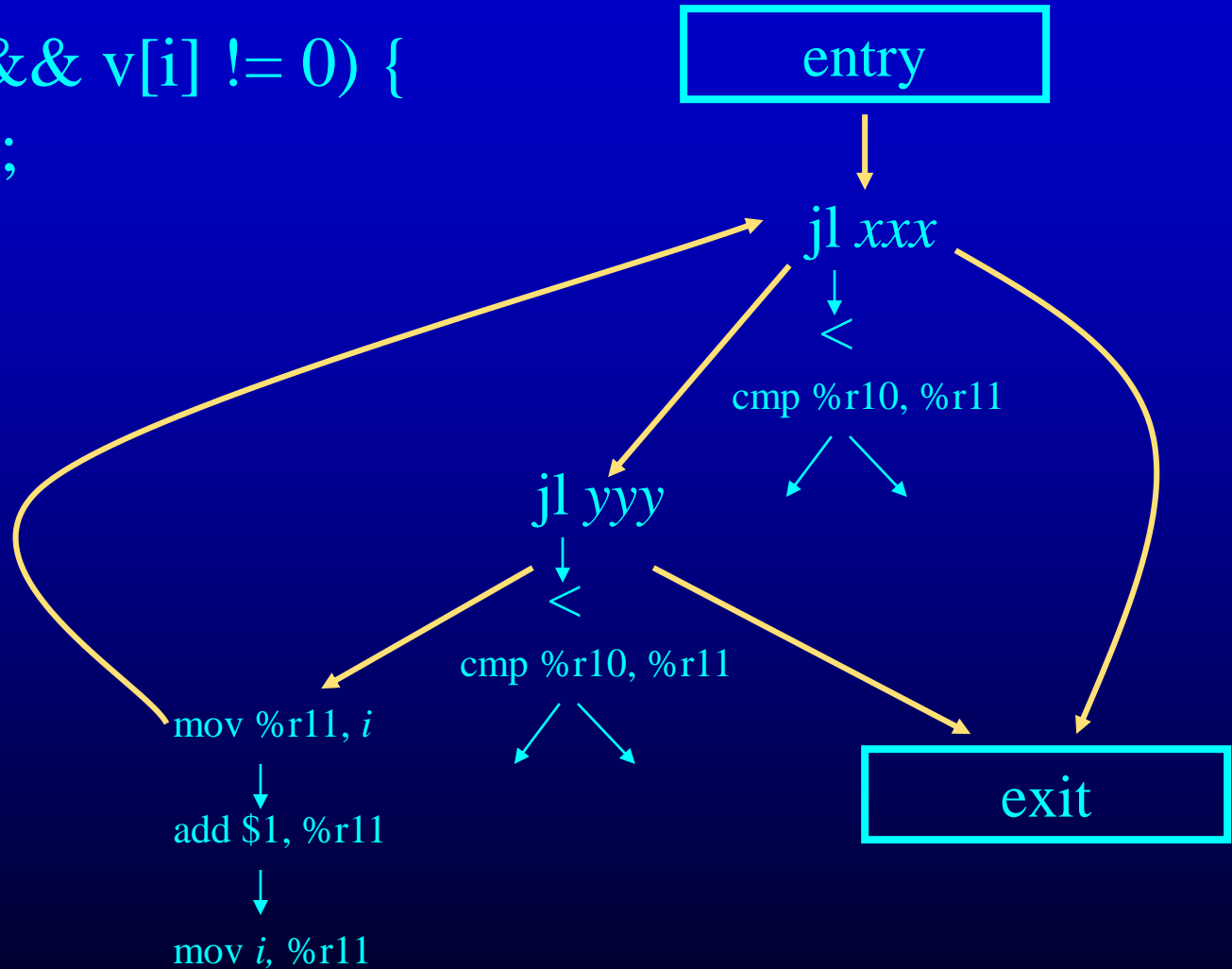
Pattern for if then else

Short-Circuit Conditionals

- In program, conditionals have a condition written as a boolean expression
 - $((i < n) \ \&\& \ (v[i] \neq 0)) \ || \ (i > k)$
- Semantics say should execute only as much as required to determine condition
 - Evaluate $(v[i] \neq 0)$ only if $(i < n)$ is true
 - Evaluate $i > k$ only if $((i < n) \ \&\& \ (v[i] \neq 0))$ is false
- Use control-flow graph to represent this short-circuit evaluation

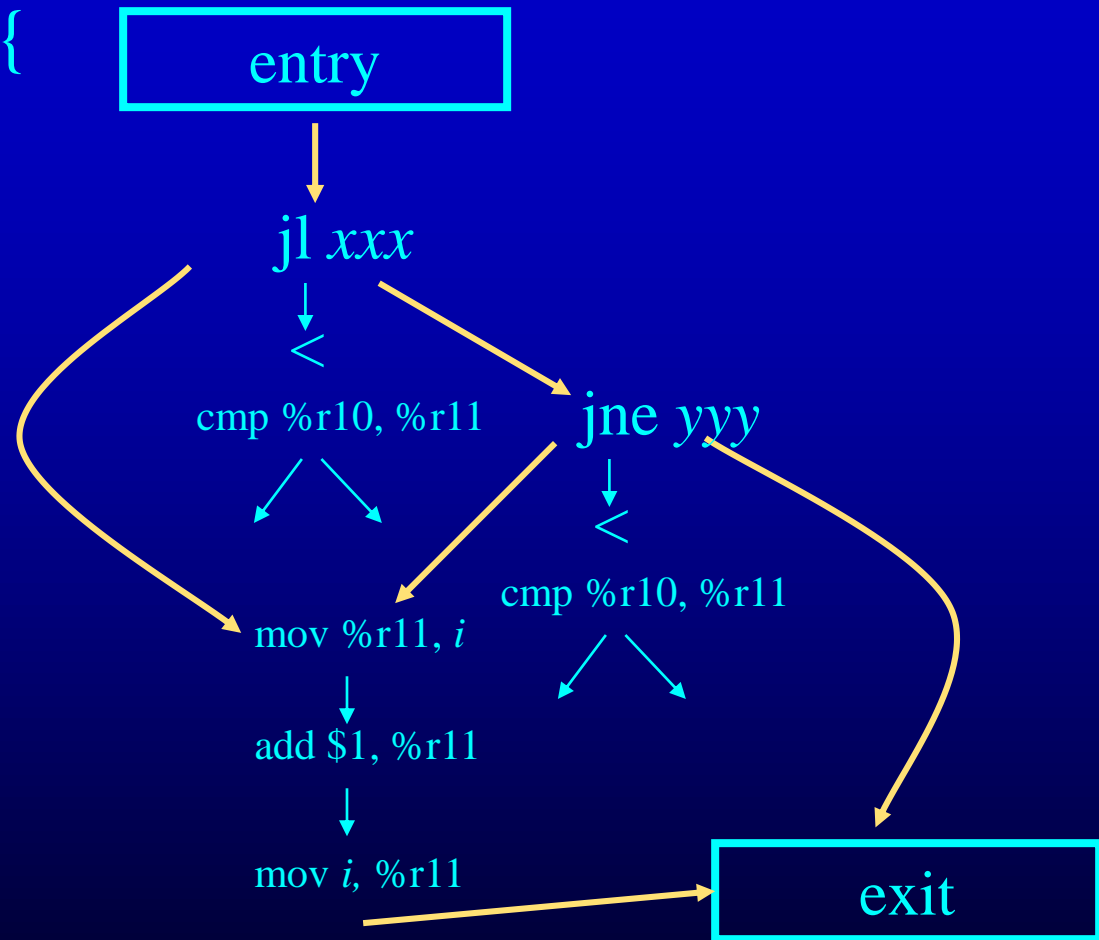
Short-Circuit Conditionals

```
while (i < n && v[i] != 0) {  
    i = i+1;  
}
```



More Short-Circuit Conditionals

```
if (a < b || c != 0) {  
    i = i+1;  
}
```



Routines for Destructuring Program Representation

destruct(**n**)

generates lowered form of structured code represented by **n**

returns (**b,e**) - **b** is begin node, **e** is end node in destructed form

shortcircuit(**c, t, f**)

generates short-circuit form of conditional represented by **c**

if **c** is true, control flows to **t** node

if **c** is false, control flows to **f** node

returns **b** - **b** is begin node for condition evaluation

new kind of node - nop node

Destructuring Seq Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**
returns (**b,e**) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form seq x y



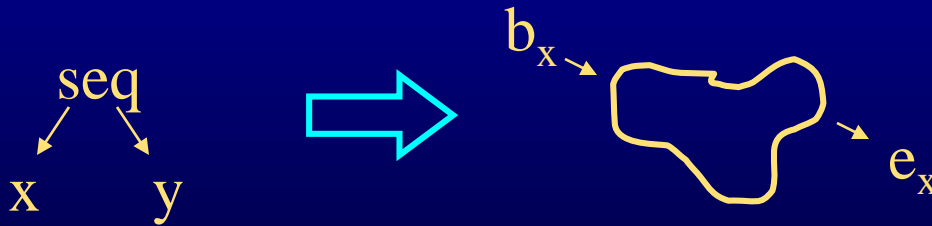
Destructuring Seq Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**

returns (b,e) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form seq **x y**

1: $(b_x, e_x) = \text{destruct}(x);$



Destructuring Seq Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**
returns (b,e) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form seq x y

1: (b_x, e_x) = destruct(x); 2: (b_y, e_y) = destruct(y);



Destructuring Seq Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**
returns (b,e) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form seq x y

1: $(b_x, e_x) = \text{destruct}(x)$; 2: $(b_y, e_y) = \text{destruct}(y)$;

3: $\text{next}(e_x) = b_y$;



Destructuring Seq Nodes

`destruct(n)`

generates lowered form of structured code represented by `n`
returns `(b,e)` - `b` is begin node, `e` is end node in destructed form
if `n` is of the form `seq x y`

- 1: `(bx,ex) = destruct(x)`; 2: `(by,ey) = destruct(y)`;
- 3: `next(ex) = by`; 4: `return (bx, ey)`;



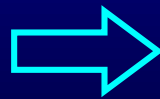
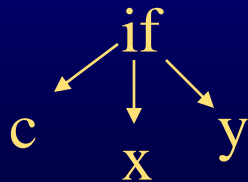
Destructuring If Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**

returns (**b,e**) - **b** is begin node, **e** is end node in destructed form

if **n** is of the form if **c x y**

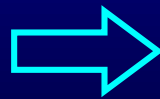
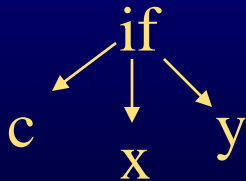


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returns (**b,e**) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form if **c x y**

1: (b_x, e_x) = destruct(**x**);

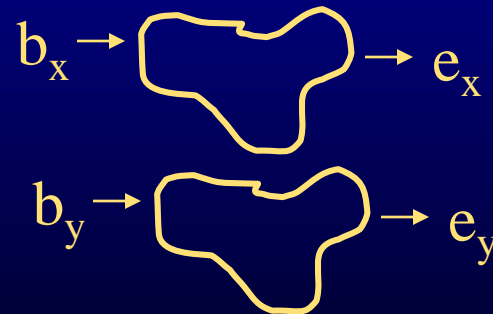
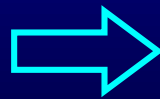
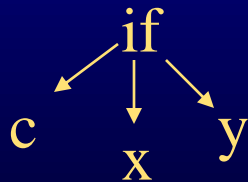


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1: (b_x, e_x) = destruct(**x**); 2: (b_y, e_y) = destruct(**y**);

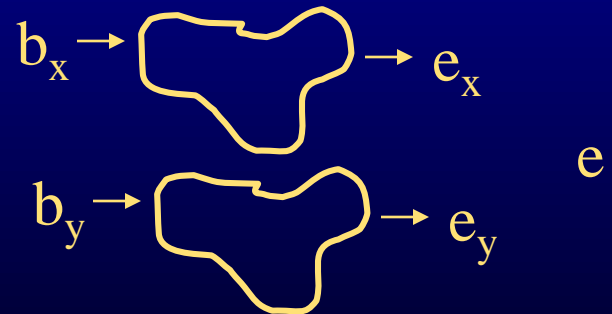
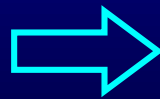
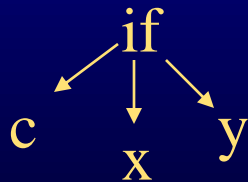


Destructuring If Nodes

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generates lowered form of structured code represented by **n**
returns (**b,e**) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form if **c x y**

- 1: (b_x, e_x) = destruct(**x**);
- 2: (b_y, e_y) = destruct(**y**);
- 3: $e = \text{new nop}$;

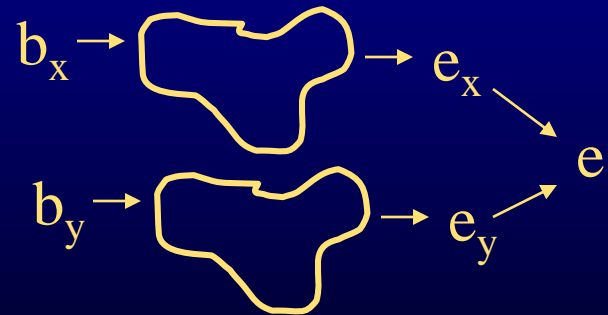
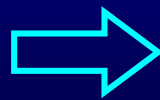
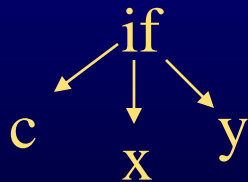


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if **n** is of the form if **c x y**

- 1: $(b_x, e_x) = \text{destruct}(x)$; 2: $(b_y, e_y) = \text{destruct}(y)$;
- 3: $e = \text{new nop}$; 4: $\text{next}(e_x) = e$; 5: $\text{next}(e_y) = e$;

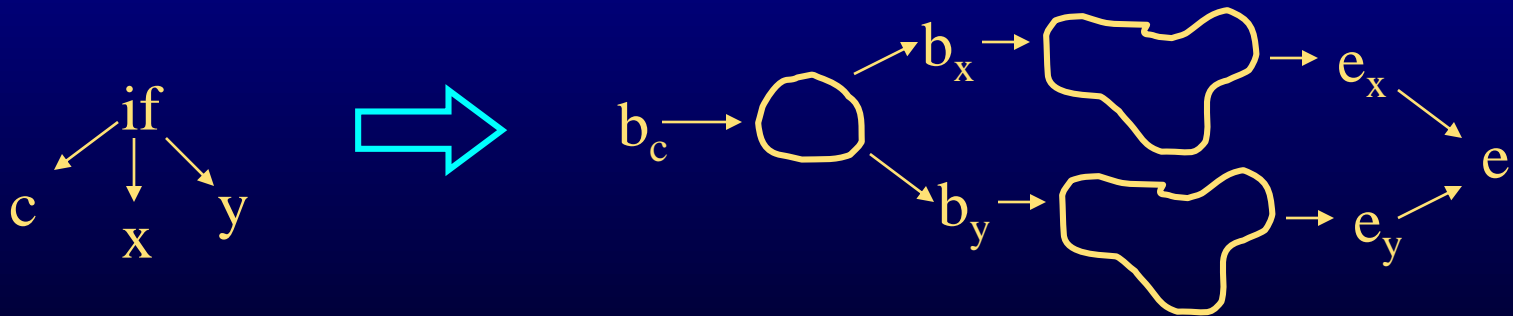


Destructuring If Nodes

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if **n** is of the form if **c x y**

- 1: $(b_x, e_x) = \text{destruct}(x)$; 2: $(b_y, e_y) = \text{destruct}(y)$;
- 3: $e = \text{new nop}$; 4: $\text{next}(e_x) = e$; 5: $\text{next}(e_y) = e$;
- 6: $b_c = \text{shortcircuit}(c, b_x, b_y)$;

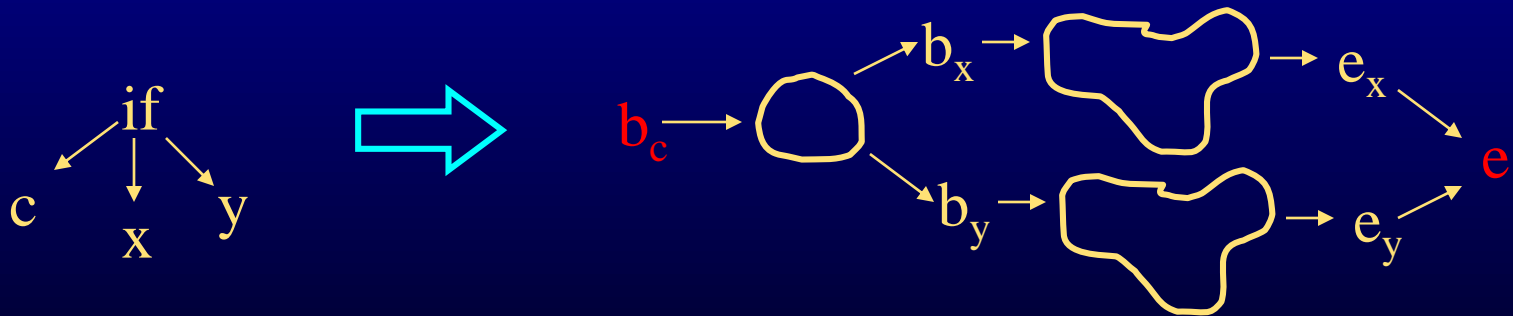


Destructuring If Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**
returns (b,e) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form if **c x y**

- 1: $(b_x, e_x) = \text{destruct}(x)$; 2: $(b_y, e_y) = \text{destruct}(y)$;
- 3: $e = \text{new nop}$; 4: $\text{next}(e_x) = e$; 5: $\text{next}(e_y) = e$;
- 6: $b_c = \text{shortcircuit}(c, b_x, b_y)$; 7: **return** (b_c, e) ;

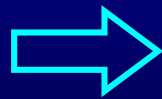


Destructuring While Nodes

destruct(**n**)

generates lowered form of structured code represented by **n**
returns (**b,e**) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form while **c x**

while
↙ ↘
c x

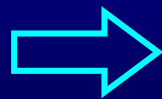
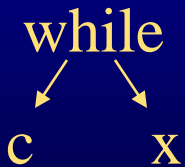


Destructuring While Nodes

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generates lowered form of structured code represented by **n**
returns (**b,e**) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form while **c x**

1: **e** = new nop;



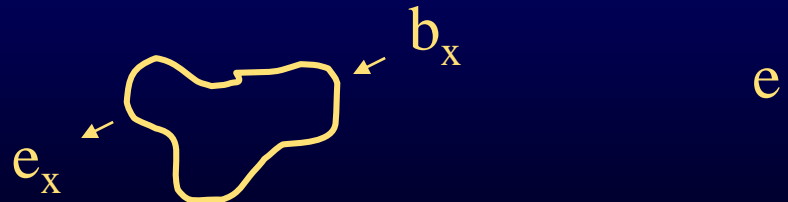
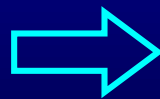
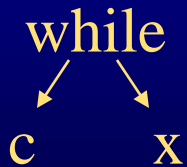
e

Destructuring While Nodes

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returns (b,e) - **b** is begin node, **e** is end node in destructed form
if **n** is of the form while **c** **x**

1: $e = \text{new nop}$; 2: $(b_x, e_x) = \text{destruct}(x)$;



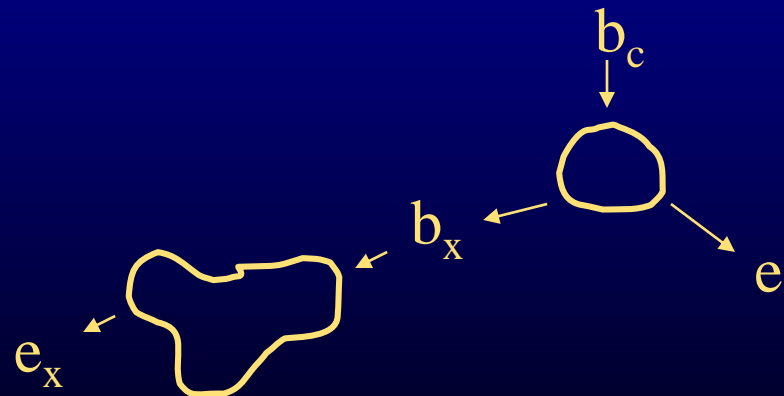
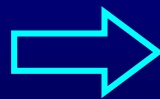
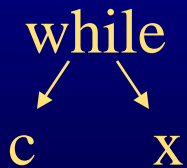
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1: $e = \text{new nop}$; 2: $(b_x, e_x) = \text{destruct}(x)$;

3: $b_c = \text{shortcircuit}(c, b_x, e)$;



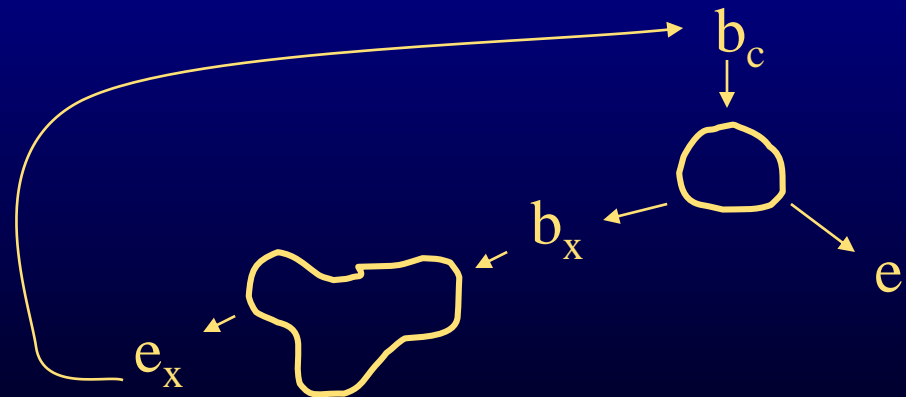
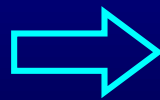
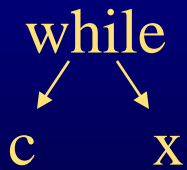
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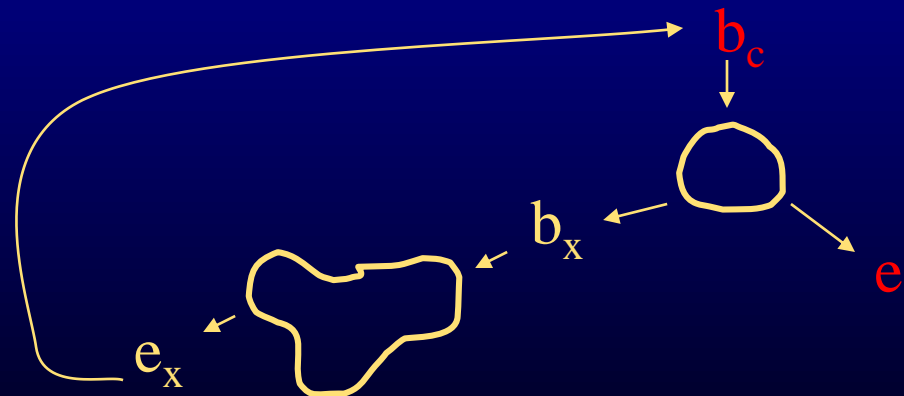
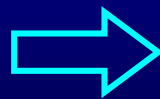
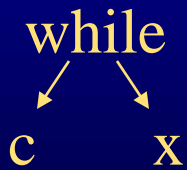
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1: $e = \text{new nop}$; 2: $(b_x, e_x) = \text{destruct}(x)$;

3: $b_c = \text{shortcircuit}(c, b_x, e)$; 4: $\text{next}(e_x) = b_c$; 5: $\text{return } (b_c, e)$;



Shortcircuiting And Conditions

`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 && c2`

`c1 && c2` 

Shortcircuiting And Conditions

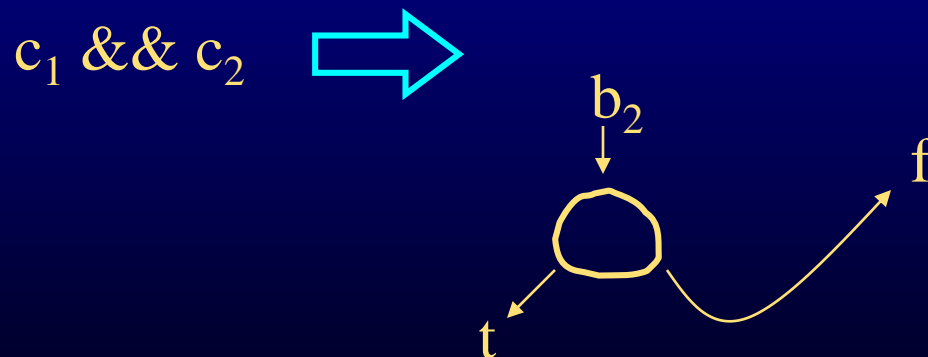
`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 && c2`

1: `b2 = shortcircuit(c2, t, f);`



Shortcircuiting And Conditions

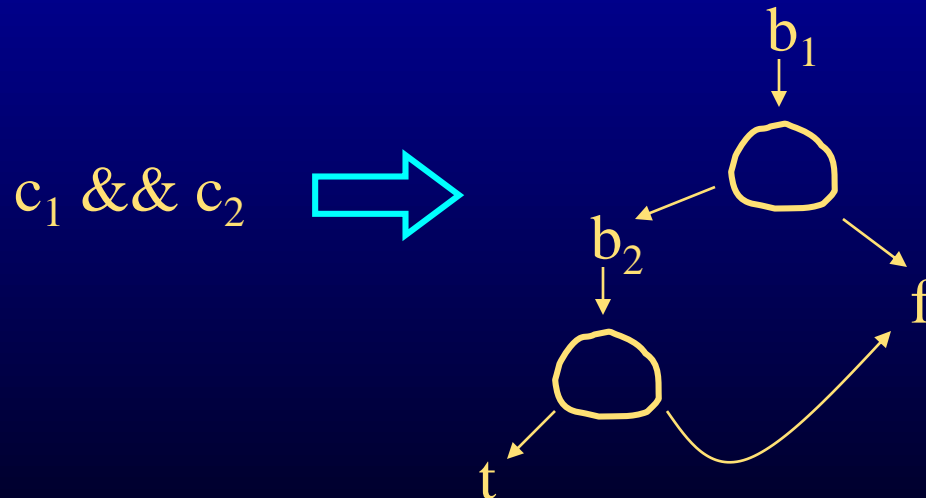
`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 && c2`

1: `b2 = shortcircuit(c2, t, f)`; 2: `b1 = shortcircuit(c1, b2, f)`;



Shortcircuiting And Conditions

`shortcircuit(c, t, f)`

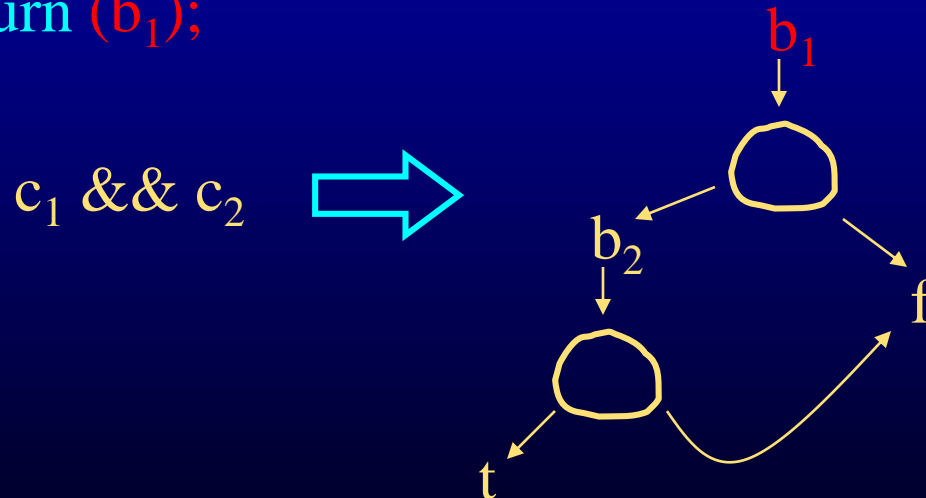
generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 && c2`

1: `b2 = shortcircuit(c2, t, f)`; 2: `b1 = shortcircuit(c1, b2, f)`;

3: `return (b1)`;



Shortcircuiting Or Conditions

`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 || c2`

`c1 || c2` 

Shortcircuiting Or Conditions

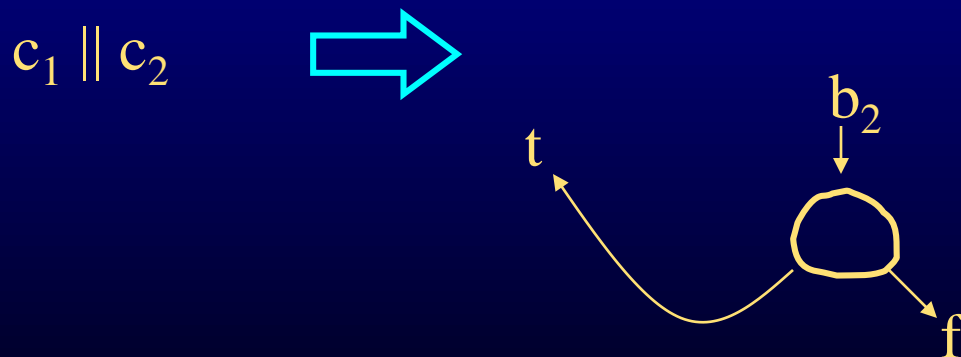
`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 || c2`

1: `b2 = shortcircuit(c2, t, f);`



Shortcircuiting Or Conditions

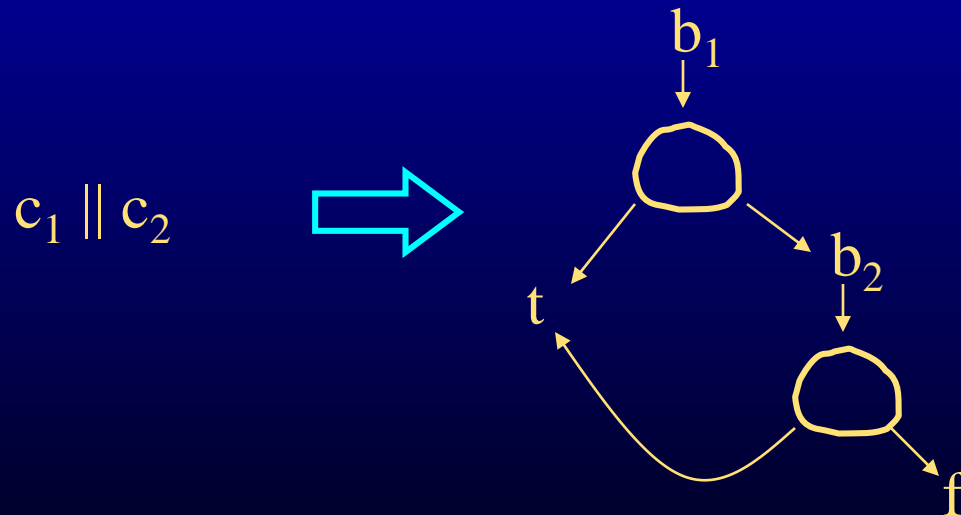
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1: `b2 = shortcircuit(c2, t, f)`; 2: `b1 = shortcircuit(c1, t, b2)`;



Shortcircuiting Or Conditions

`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

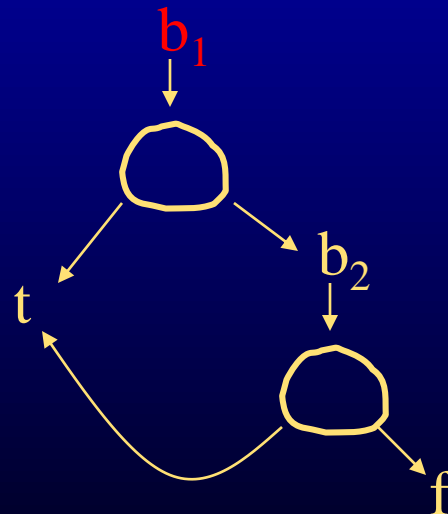
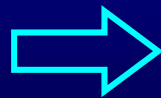
returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `c1 || c2`

1: `b2 = shortcircuit(c2, t, f)`; 2: `b1 = shortcircuit(c1, t, b2)`;

3: `return (b1)`;

`c1 || c2`



Shortcircuiting Not Conditions

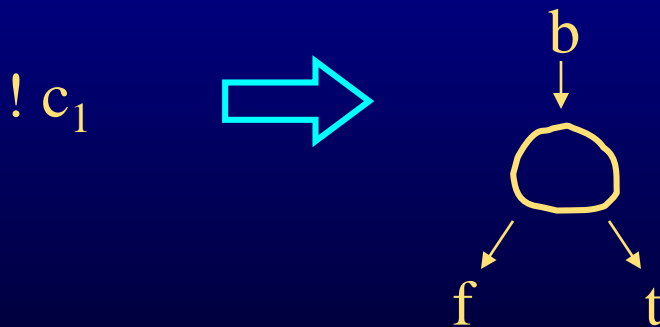
`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

if `c` is of the form `! c1`

1: `b = shortcircuit(c1, f, t); return(b);`



Computed Conditions

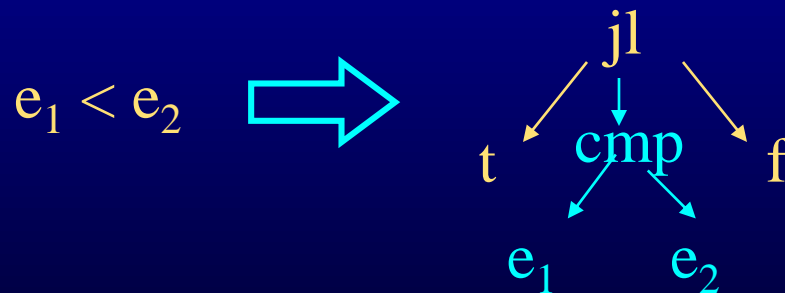
`shortcircuit(c, t, f)`

generates shortcircuit form of conditional represented by `c`

returns `b` - `b` is begin node of shortcircuit form

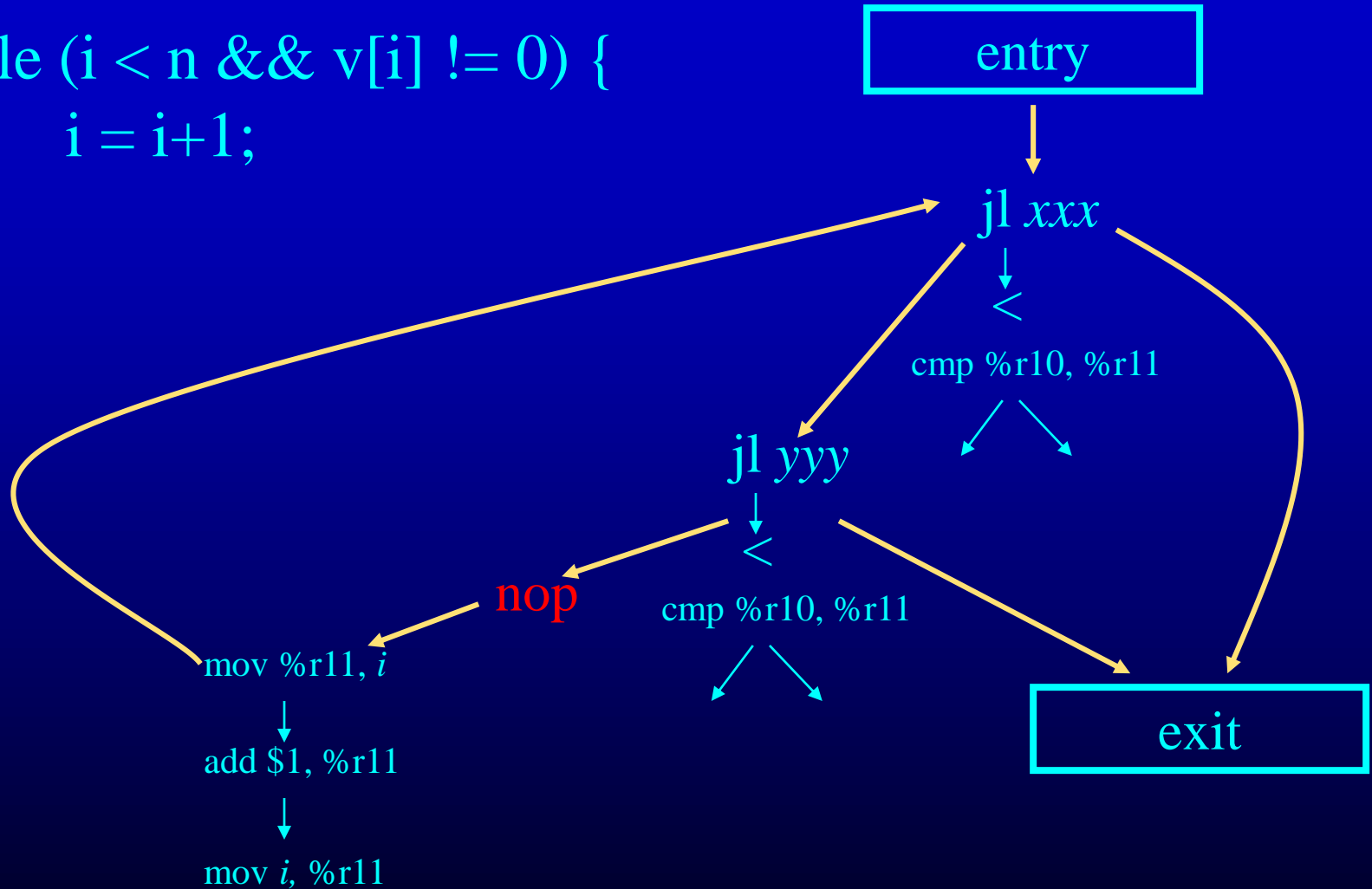
if `c` is of the form $e_1 < e_2$

1: `b = new cbr($e_1 < e_2$, t, f)`; 2: `return (b)`;

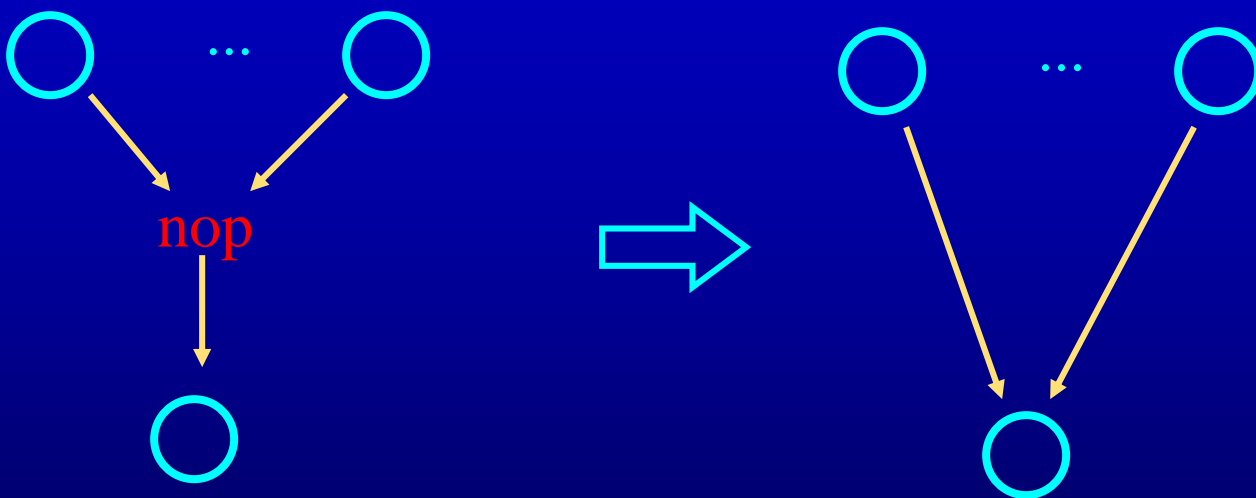


Nops In Destructured Representation

```
while (i < n && v[i] != 0) {  
    i = i+1;  
}
```



Eliminating Nops Via Peephole Optimization



Linearizing CFG to Assembler

- Generate labels for edge targets at branches
 - Labels will correspond to branch targets
 - Can use patterns for this
- Generate code for statements/conditional expressions
- Generate code for procedure entry/exit

Outline

- Generation of statements
- Generation of control flow
- x86-64 Processor
- Guidelines in writing a code generator

Guidelines for the code generator

- Lower the abstraction level slowly
 - Do many passes, that do few things (or one thing)
 - Easier to break the project down, generate and debug
- Keep the abstraction level consistent
 - IR should have ‘correct’ semantics at all time
 - At least you should know the semantics
 - You may want to run some of the optimizations between the passes.
- Write sanity checks, consistency checks, use often

Guidelines for the code generator

- Do the simplest but dumb thing
 - it is ok to generate $0 + 1*x + 0*y$
 - Code is painful to look at; let optimizations improve it
- Make sure you know what can be done at...
 - Compile time in the compiler
 - Runtime using generated code

Guidelines for the code generator

- Remember that optimizations will come later
 - Let the optimizer do the optimizations
 - Think about what optimizer will need and structure your code accordingly
 - Example: Register allocation, algebraic simplification, constant propagation
- Setup a good testing infrastructure
 - regression tests
 - If a input program creates a bug, use it as a regression test
 - Learn good bug hunting procedures
 - Example: binary search , delta debugging