

## **Parallelization**

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## Outline

- Why Parallelism
- Parallel Execution
- Parallelizing Compilers
- Dependence Analysis
- Increasing Parallelization Opportunities

# **Moore's Law**



Number of Transistors

#### **Uniprocessor Performance (SPECint)**



1978 1980 1982 1984 1986 1988 1990 1992 1994 1996 1998 2000 2002 2004 2006 2008 2010 2012 2014 2016

#### **Multicores Are Here!**



# **Issues with Parallelism**

- Amdhal's Law
  - Any computation can be analyzed in terms of a portion that must be executed sequentially, Ts, and a portion that can be executed in parallel, Tp. Then for n processors:
  - T(n) = Ts + Tp/n
  - $T(\infty) = Ts$ , thus maximum speedup (Ts + Tp) /Ts
- Load Balancing
  - The work is distributed among processors so that *all* processors are kept busy when parallel task is executed.
- Granularity
  - The size of the parallel regions between synchronizations or the ratio of computation (useful work) to communication (overhead).

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## **Types of Parallelism**

 Instruction Level Parallelism (ILP)

 $\rightarrow$  Scheduling and Hardware

 Task Level Parallelism (TLP)  $\rightarrow$  Mainly by hand

- Loop Level Parallelism (LLP) or Data Parallelism
- Pipeline Parallelism
- Divide and Conquer Parallelism

- $\rightarrow$  Hand or Compiler Generated
- $\rightarrow$  Hardware or Streaming
- $\rightarrow$  Recursive functions

# Why Loops?

- 90% of the execution time in 10% of the code
   Mostly in loops
- If parallel, can get good performance
   Load balancing
- Relatively easy to analyze

#### **Programmer Defined Parallel Loop**

- FORALL
  - No "loop carried dependences"
  - Fully parallel

- FORACROSS
  - Some "loop carried dependences"





#### **Parallel Execution**

• Example FORPAR I = 0 to N

A[I] = A[I] + 1

- Block Distribution: Program gets mapped into Iters = ceiling(N/NUMPROC);
   FOR P = 0 to NUMPROC-1
   FOR I = P\*Iters to MIN((P+1)\*Iters, N)
   A[I] = A[I] + 1
- SPMD (Single Program, Multiple Data) Code
   If(myPid == 0) {

```
...
Iters = ceiling(N/NUMPROC);
Barrier();
FOR I = myPid*Iters to MIN((myPid+1)*Iters, N)
        A[I] = A[I] + 1
Barrier();
```

### **Parallel Execution**

• Example

FORPAR I = 0 to N A[I] = A[I] + 1

#### • Block Distribution: Program gets mapped into

```
Iters = ceiling(N/NUMPROC);
FOR P = 0 to NUMPROC-1
FOR I = P*Iters to MIN((P+1)*Iters, N)
        A[I] = A[I] + 1
```

```
    Code fork a function
```

```
Iters = ceiling(N/NUMPROC);
ParallelExecute(func1);
...
void func1(integer myPid)
{
   FOR I = myPid*Iters to MIN((myPid+1)*Iters, N)
        A[I] = A[I] + 1
}
```

# **Parallel Execution**

#### SPMD

- Need to get all the processors execute the control flow
  - Extra synchronization overhead or redundant computation on all processors or both
- Stack: Private or Shared?
- Fork
  - Local variables not visible within the function
    - Either make the variables used/defined in the loop body global or pass and return them as arguments
    - Function call overhead

## **Parallel Thread Basics**

- Create separate threads
  - Create an OS thread
    - (hopefully) it will be run on a separate core
  - pthread\_create(&thr, NULL, &entry\_point, NULL)
  - Overhead in thread creation
    - Create a separate stack
    - Get the OS to allocate a thread
- Thread pool
  - Create all the threads (= num cores) at the beginning
  - Keep N-1 idling on a barrier, while sequential execution
  - Get them to run parallel code by each executing a function
  - Back to the barrier when parallel region is done

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### **Parallelizing Compilers**

Finding FORALL Loops out of FOR loops

#### • Examples

FOR I = 0 to 5 A[I] = A[I] + 1

```
FOR I = 0 to 5
A[I] = A[I+6] + 1
```

```
For I = 0 to 5
A[2*I] = A[2*I + 1] + 1
```

- N deep loops  $\rightarrow$  n-dimensional discrete cartesian space
  - Normalized loops: assume step size = 1



Iterations are represented as coordinates in iteration space
 i - [i<sub>1</sub>, i<sub>2</sub>, i<sub>3</sub>,..., i<sub>n</sub>]

- N deep loops  $\rightarrow$  n-dimensional discrete cartesian space
  - Normalized loops: assume step size = 1



- Iterations are represented as coordinates in iteration space
- Sequential execution order of iterations → Lexicographic order
   [0,0], [0,1], [0,2], ..., [0,6], [0,7],
   [1,1], [1,2], ..., [1,6], [1,7],
   [2,2], ..., [2,6], [2,7],
   [6,6], [6,7],
   [6,6], [6,7],
   [6,7],
   [6,7],
   [6,6], [6,7],
   [6,7],
   [1,1],
   [1,1],
   [1,2],
   [1,2],
   [1,2],
   [1,2],
   [1,6],
   [1,7],
   [1,6],
   [1,7],
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   [2,6],
   [2,6],
   [2,7],
   [2,6],
   [2,6],
   [2,6],
   [2,6],
   [2

- N deep loops  $\rightarrow$  n-dimensional discrete cartesian space
  - Normalized loops: assume step size = 1



- Iterations are represented as coordinates in iteration space
- Sequential execution order of iterations → Lexicographic order
- Iteration i is lexicograpically less than j, i < j iff there exists c s.t. i<sub>1</sub> = j<sub>1</sub>, i<sub>2</sub> = j<sub>2</sub>,... i<sub>c-1</sub> = j<sub>c-1</sub> and i<sub>c</sub> < j<sub>c</sub>

- N deep loops  $\rightarrow$  n-dimensional discrete cartesian space
  - Normalized loops: assume step size = 1



- An affine loop nest
  - Loop bounds are integer linear functions of constants, loop constant variables and outer loop indexes
  - Array accesses are integer linear functions of constants, loop constant variables and loop indexes

- N deep loops  $\rightarrow$  n-dimensional discrete cartesian space
  - Normalized loops: assume step size = 1



Affine loop nest → Iteration space as a set of liner inequalities

 0 ≤ I
 I ≤ 6
 I ≤ J
 J ≤ 7

## **Data Space**

M dimensional arrays → m-dimensional discrete cartesian space
 a hypercube

Integer A(10)	0	1	2	3	4	5	6	7	8	9

Float B(5, 6)



# Dependences

• True dependence

a =

= a

- Anti dependence
  - = a
  - a =
- Output dependence
  - a a
- Definition:

Data dependence exists for a dynamic instance i and j iff

- either i or j is a write operation
- i and j refer to the same variable
- i executes before j
- How about array accesses within loops?

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FOR I = 0 to 5

A[I] = A[I] + 1

Iteration Space	Data Space
0 1 2 3 4 5	0 1 2 3 4 5 6 7 8 9 10 111

#### Array Accesses in a loop FOR I = 0 to 5 A[I] = A[I] + 1

	Iteration Space										Data Space									
	0	1	2	3	4	5		0 □-	1	2	3	4	5	6	7	8	9	10	111	.2
= A[I] A[I]																				
- A[I] A[I]																				
= A[I] A[I]										ł										
= A[I] A[I]																				
= A[I] A[I]																				
= A[I] A[I] <sub>Saman Amarasinghe</sub>							26								6.03		©MI	1	2006	



FOR I = 0 to 5 A[I+1] = A[I] + 1

	Ite	ratio	on S	Spa	ce
0	1	2	3	4	5
<u> </u>					-0

	Data Space														
0	1	2	3	4	5	6	7	8	9	10	11	12			
<b>—</b>		0-		0						0					





FOR I = 0 to 5

A[I] = A[I+2] + 1

		Ite	rati	on S	Spa	ce Data Space													
	0	1	2	3	4	5	0 ┏-	1	2	3	4	5	6	7	8	9	10	111	.2
= A[I+2] A[I]																			
- A[I+2] A[I]																			
= A[I+2] A[I]									Ľ										
= A[I+2] A[I]												1							
= A[I+2] A[I]																			
= A[I+2] A[I] <sub>Saman Amarasinghe</sub>						28								<b>6.03</b>		©MI		1 2006	

FOR I = 0 to 5

A[2\*I] = A[2\*I+1] + 1



#### **Distance Vectors**

 A loop has a distance d if there exist a data dependence from iteration i to j and d = j-i



# **Multi-Dimensional Dependence**





#### **Multi-Dimensional Dependence**











dv =

#### **Outline**

- Dependence Analysis
- Increasing Parallelization Opportunities

#### What is the Dependence?



#### What is the Dependence?



# What is the Dependence?




### What is the Dependence?



FOR I = 1 to n FOR J = 1 to n A[I] = A[I-1] + 1



### What is the Dependence?











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## What is the Dependence?





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# **Recognizing FORALL Loops**

- For every pair of array acceses to the same array
  - If the first access has at least one dynamic instance (an iteration) in which it refers to a location in the array that the second access also refers to in at least one of the later dynamic instances (iterations).
  - Then there is a data dependence between the statements
- (Note that same array can refer to itself output dependences)

#### Definition

- Loop-carried dependence: dependence that crosses a loop boundary
- <sup>-</sup> If there are no loop carried dependences  $\rightarrow$  parallelizable

### **Data Dependence Analysis**

- I: Distance Vector method
- II: Integer Programming

### **Distance Vector Method**

• The i<sup>th</sup> loop is parallelizable for all dependence  $d = [d_1, ..., d_i, ...d_n]$ either one of  $d_1, ..., d_{i-1}$  is > 0 or all  $d_1, ..., d_i = 0$ 

# Is the Loop Parallelizable?



### **Are the Loops Parallelizable?**





No Yes







dv =

## **Are the Loops Parallelizable?**



$$dv = \begin{bmatrix} 1 \\ * \end{bmatrix}$$









## **Integer Programming Method**

• Example

FOR I = 0 to 5
 A[I+1] = A[I] + 1

- Is there a loop-carried dependence between A[I+1] and A[I]
  - Is there two distinct iterations  $i_w$  and  $i_r$  such that A[i\_w+1] is the same location as A[i\_r]

 $- \exists \text{ integers } i_w, i_r \quad 0 \leq i_w, i_r \leq 5 \quad i_w \neq i_r \quad i_w + 1 = i_r$ 

- Is there a dependence between A[I+1] and A[I+1]
  - Is there two distinct iterations  $i_1$  and  $i_2$  such that A[i\_1+1] is the same location as A[i\_2+1]

 $- \exists \text{ integers } i_1, i_2 \qquad 0 \leq i_1, i_2 \leq 5 \qquad i_1 \neq i_2 \qquad i_1 + 1 = i_2 + 1$ 

### **Integer Programming Method**

FOR I = 0 to 5
 A[I+1] = A[I] + 1

- Formulation
  - $\exists an integer vector i such that Âi ≤ b where A is an integer matrix and b is an integer vector$

### **Iteration Space**

FOR I = 0 to 5 A[I+1] = A[I] + 1

 N deep loops → n-dimensional discrete cartesian space

 Affine loop nest → Iteration space as a set of liner inequalities

 $0 \le I$  $I \le 6$  $I \le J$  $J \le 7$ 



# **Integer Programming Method**

FOR I = 0 to 5 A[I+1] = A[I] + 1

- Formulation
  - $\exists an integer vector i such that Âi ≤ b where A is an integer matrix and b is an integer vector$
- Our problem formulation for A[i] and A[i+1]
   ∃ integers i<sub>w</sub>, i<sub>r</sub> 0 ≤ i<sub>w</sub>, i<sub>r</sub> ≤ 5 i<sub>w</sub> ≠ i<sub>r</sub> i<sub>w</sub>+1 = i<sub>r</sub>
  - $-i_w \neq i_r$  is not an affine function
    - divide into 2 problems
    - Problem 1 with  $i_w < i_r$  and problem 2 with  $i_r < i_w$
    - If either problem has a solution  $\rightarrow$  there exists a dependence
  - How about  $i_w + 1 = i_r$ 
    - Add two inequalities to single problem

$$i_w + 1 \le i_r$$
, and  $i_r \le i_w + 1$ 

### **Integer Programming Formulation**

FOR I = 0 to 5 A[I+1] = A[I] + 1

- Problem 1
  - $\begin{array}{l} 0 \leq i_{w} \\ i_{w} \leq 5 \\ 0 \leq i_{r} \\ i_{r} \leq 5 \\ i_{w} \leq i_{r} \\ i_{w} + 1 \leq i_{r} \\ i_{w} + 1 \leq i_{r} \\ i_{r} \leq i_{w} + 1 \end{array}$

### **Integer Programming Formulation**

• Problem 1

FOR I = 0 to 5 A[I+1] = A[I] + 1

### **Integer Programming Formulation**

- Problem 51



• and problem 2 with  $i_r < i_w$ 

### Generalization

- An affine loop nest
   FOR i<sub>1</sub> = f<sub>11</sub>(c<sub>1</sub>...c<sub>k</sub>) to I<sub>u1</sub>(c<sub>1</sub>...c<sub>k</sub>)
   FOR i<sub>2</sub> = f<sub>12</sub>(i<sub>1</sub>, c<sub>1</sub>...c<sub>k</sub>) to I<sub>u2</sub>(i<sub>1</sub>, c<sub>1</sub>...c<sub>k</sub>)
   .....
   FOR i<sub>n</sub> = f<sub>1n</sub>(i<sub>1</sub>...i<sub>n-1</sub>, c<sub>1</sub>...c<sub>k</sub>) to I<sub>un</sub>(i<sub>1</sub>...i<sub>n-1</sub>, c<sub>1</sub>...c<sub>k</sub>)
   A[f<sub>a1</sub>(i<sub>1</sub>...i<sub>n</sub>, c<sub>1</sub>...c<sub>k</sub>), f<sub>a2</sub>(i<sub>1</sub>...i<sub>n</sub>, c<sub>1</sub>...c<sub>k</sub>), ..., f<sub>am</sub>(i<sub>1</sub>...i<sub>n</sub>, c<sub>1</sub>...c<sub>k</sub>)]
- Solve 2\*n problems of the form

• 
$$\mathbf{i}_1 = \mathbf{j}_1$$
,  $\mathbf{i}_2 = \mathbf{j}_2$ ,.....  $\mathbf{i}_{n-1} = \mathbf{j}_{n-1}$ ,  $\mathbf{i}_n < \mathbf{j}$   
•  $\mathbf{i}_1 = \mathbf{j}_1$ ,  $\mathbf{i}_2 = \mathbf{j}_2$ ,.....  $\mathbf{i}_{n-1} = \mathbf{j}_{n-1}$ ,  $\mathbf{j}_n < \mathbf{i}$   
•  $\mathbf{i}_1 = \mathbf{j}_1$ ,  $\mathbf{i}_2 = \mathbf{j}_2$ ,.....  $\mathbf{i}_{n-1} < \mathbf{j}_{n-1}$   
•  $\mathbf{i}_1 = \mathbf{j}_1$ ,  $\mathbf{i}_2 = \mathbf{j}_2$ ,.....  $\mathbf{j}_{n-1} < \mathbf{i}_{n-1}$ 

• 
$$i_1 = j_1, i_2 < j_2$$
  
•  $i_1 = i_1 + i_2 < j_2$ 

• 
$$i_1 < j_1$$

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- Why Parallelism
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- Increasing Parallelization Opportunities

## Increasing Parallelization Opportunities

- Scalar Privatization
- Reduction Recognition
- Induction Variable Identification
- Array Privatization
- Loop Transformations
- Granularity of Parallelism
- Interprocedural Parallelization

### **Scalar Privatization**

### • Example

- FOR i = 1 to n
  X = A[i] \* 3;
  B[i] = X;
- Is there a loop carried dependence? What is the type of dependence?

## **Privatization**

- Analysis:
  - Any anti- and output- loop-carried dependences
- Eliminate by assigning in local context
   FOR i = 1 to n
   integer Xtmp;
   [i] \* 3;
   B[i] = Xtmp;
- Eliminate by expanding into an array
   FOR i = 1 to n
   Xtmp[i] = A[i] \* 3;
   B[i] = Xtmp[i];

### **Privatization**

- Need a final assignment to maintain the correct value after the loop nest
- Eliminate by assigning in local context

```
FOR i = 1 to n
integer Xtmp;
Xtmp = A[i] * 3;
B[i] = Xtmp;
if(i == n) X = Xtmp
```

• Eliminate by expanding into an array

```
FOR i = 1 to n
    Xtmp[i] = A[i] * 3;
    B[i] - Xtmp[i];
```

```
X = Xtmp[n];
```

### **Another Example**

- How about loop-carried true dependences?
  - Example
    - FOR i = 1 to n

X = X + A[i];

• Is this loop parallelizable?

## **Reduction Recognition**

• Reduction Analysis:

Only associative operations

The result is never used within the loop

#### Transformation

```
Integer Xtmp[NUMPROC];
Barrier();
FOR i = myPid*Iters to MIN((myPid+1)*Iters, n)
        Xtmp[myPid] = Xtmp[myPid] + A[i];
Barrier();
If(myPid == 0) {
   FOR p = 0 to NUMPROC-1
        X = X + Xtmp[p];
```

...

### **Induction Variables**

• Example

FOR i = 0 to N

 $A[i] = 2^{i};$ 

### After strength reduction

- t = 1
  FOR i = 0 to N
  A[i] = t;
  t = t\*2;
- What happened to loop carried dependences?
- Need to do opposite of this!
  - Perform induction variable analysis
  - Rewrite IVs as a function of the loop variable

# **Array Privatization**

- Similar to scalar privatization
- However, analysis is more complex
  - Array Data Dependence Analysis: Checks if two iterations access the same location
  - Array Data Flow Analysis:
     Checks if two iterations access the same value
- Transformations
  - Similar to scalar privatization
  - Private copy for each processor or expand with an additional dimension

## **Loop Transformations**

- A loop may not be parallel as is
- Example

FOR i = 1 to N-1
FOR j = 1 to N-1
A[i,j] = A[i,j-1] + A[i-1,j];



### **Loop Transformations**

- A loop may not be parallel as is
- Example

FOR i = 1 to N-1
FOR j = 1 to N-1
A[i,j] = A[i,j-1] + A[i-1,j];



### **Granularity of Parallelism**

#### • Example

FOR i = 1 to N-1
FOR j = 1 to N-1
A[i,j] = A[i,j] + A[i-1,j];

• Gets transformed into

```
FOR i = 1 to N-1
Barrier();
FOR j = 1+ myPid*Iters to MIN((myPid+1)*Iters, n-1)
A[i,j] = A[i,j] + A[i-1,j];
Barrier();
```

- Inner loop parallelism can be expensive
  - Startup and teardown overhead of parallel regions
  - Lot of synchronization
  - Can even lead to slowdowns



## **Granularity of Parallelism**

• Inner loop parallelism can be expensive

### Solutions

 Don't parallelize if the amount of work within the loop is too small

or

– Transform into outer-loop parallelism

### **Outer Loop Parallelism**

#### • Example

FOR i = 1 to N-1
FOR j = 1 to N-1
A[i,j] = A[i,j] + A[i-1,j];

#### After Loop Transpose

FOR j = 1 to N-1
FOR i = 1 to N-1
A[i,j] = A[i,j] + A[i-1,j];

#### • Get mapped into

```
Barrier();
FOR j = 1+ myPid*Iters to MIN((myPid+1)*Iters, n-1)
FOR i = 1 to N-1
A[i,j] = A[i,j] + A[i-1,j];
Barrier();
```





### **Unimodular Transformations**

- Interchange, reverse and skew
- Use a matrix transformation  $I_{new} = A I_{old}$
- Interchange



Skew

$$\begin{bmatrix} i_{new} \\ j_{new} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} i_{old} \\ j_{old} \end{bmatrix}$$

$$\begin{bmatrix} i_{new} \\ j_{new} \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} i_{old} \\ j_{old} \end{bmatrix}$$

$$\begin{bmatrix} i_{new} \\ j_{new} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} i_{old} \\ j_{old} \end{bmatrix}$$

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# Legality of Transformations

 Unimodular transformation with matrix A is valid iff.
 For all dependence vectors v the first non-zero in Av is positive



## **Interprocedural Parallelization**

- Function calls will make a loop unparallelizatble
  - Reduction of available parallelism
  - A lot of inner-loop parallelism
- Solutions
  - Interprocedural Analysis
  - Inlining

### **Interprocedural Parallelization**

### Issues

- Same function reused many times
- Analyze a function on each trace  $\rightarrow$  Possibly exponential
- Analyze a function once  $\rightarrow$  unrealizable path problem

#### Interprocedural Analysis

- Need to update all the analysis
- Complex analysis
- Can be expensive

### • Inlining

- Works with existing analysis
- Large code bloat  $\rightarrow$  can be very expensive

# Summary

- Multicores are here
  - Need parallelism to keep the performance gains
  - Programmer defined or compiler extracted parallelism
- Automatic parallelization of loops with arrays
  - Requires Data Dependence Analysis
  - Iteration space & data space abstraction
  - An integer programming problem
- Many optimizations that'll increase parallelism
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